# Servo Actuator - Quick Start Guide

Required:	<b>Optional:</b>				
FA-PO Linear Actuator LAC Circuit Board	Potentiometer USB Cable				
12V Power Supply or Battery	Radio Controlled Receiver			Wire Color	Pin Label
				White	P+
				Yellow	Р
<u>Step 1:</u>					M+
					M-
Connect the actuator to the LAC using the green screw terminals. See diagrams on reverse				Blue	P-
<u>Step 2:</u>		Potentiometer	Pin Label		
Option A – Connect a potentiometer for manual control.		Reference +	P+		
<u>Option A</u> – Connect a potentionneter for	1 manual control.	Reference -	P-		
		Wiper	VC		

<u>Option B</u> – Connect an RC Receiver for remote control. You can use either the receiver	<b>RC Receiver</b>	Pin Label
power or an external power supply, but not both, as it will damage the receiver. Cut the red	Black	-
wire from the receiver to prevent damage when using an external power supply or BEC.	Red	Not Connected
	White	RC

Option C – Connect a USB cable for computer control. You will need to install the LAC driver from www.firgelli.com

For more control options, like PLC, PWM or DAQ control, see the LAC datasheet at www.firgelli.com.

#### <u>Step 3:</u>

Set up the default configuration by turning all four of the blue potentiometers fully **clockwise**. Turn the one labeled "Accuracy" back 1/8 of a turn for quieter operation.

#### Step 4:

Connect your power supply or battery, and test for basic operation. If the actuator extends to one end and then stops responding, swap the white and blue actuator wires and test again.

Polarity	Pin Label
Positive	+
Negative	-

#### Step 5: (Optional)

Adjust the four blue potentiometers as desired. Load the new settings by turning the power off then on.

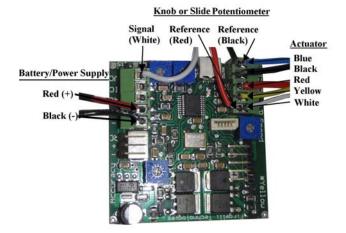
- Accuracy This potentiometer controls how close the actuator has to be to the commanded position before the motor is turned off. Setting this to fully clockwise may significantly increase how loud the actuator is.
  Speed This potentiometer controls how fast the actuator moves. Rotate counter clockwise to reduce the speed. Actuator noise will increase when speed is reduced.
  Limits These two potentiometers are digital limit switches. They control the minimum and maximum actuator
  - imits These two potentiometers are digital limit switches. They control the minimum and maximum actuator positions (How far in and how far out the shaft is allowed to move).

#### Advanced Setup, Tuning and Mounting Information:

For more information on the actuator, refer to the FA-PO documentation at www.firgelliauto.com.

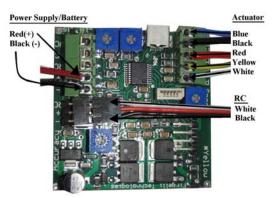
For example code and more information on the controller board, refer to the LAC board at www.firgelli.com.

## **Option A:** Potentiometer Control





## **Option B:** RC Control



### Do not connect the Red Wire



## **Option C:** USB Control

