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## MX25U4033E

### 1.8V, 4M-BIT [x 1/x 2/x 4] <br> CMOS MXSMIO ${ }^{\circledR}$ (SERIAL MULTI I/O) <br> FLASH MEMORY

## Key Features

- HOLD feature
- Multi I/O Support - Single I/O, Dual I/O and Quad I/O
- Auto Erase and Auto Program Algorithm
- Low Power Consumption

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## 4M-BIT [x 1/x 2/x 4] 1.8V CMOS MXSMIO ${ }^{\circledR}$ (SERIAL MULTI I/O) FLASH MEMORY

## 1. FEATURES

## GENERAL

- Single Power Supply Operation
- 1.65 to 2.0 volt for read, erase, and program operations
- Supports Serial Peripheral Interface -- Mode 0 and Mode 3
- $4 \mathrm{M}: 4,194,304 \times 1$ bit structure or $2,097,152 \times 2$ bits (two I/O read mode) structure or $1,048,576 \times 4$ bits (four I/O read mode) structure
- 128 Equal Sectors with 4 K byte each
- Any Sector can be erased individually
- 16 Equal Blocks with 32 K byte each
- Any Block can be erased individually
- 8 Equal Blocks with 64K byte each
- Any Block can be erased individually
- Program Capability
- Byte base
- Page base (256 bytes)
- Latch-up protected to 100 mA from -1 V to $\mathrm{Vcc}+1 \mathrm{~V}$


## PERFORMANCE

- High Performance
- Fast read
- $1 \mathrm{I} / \mathrm{O}: 80 \mathrm{MHz}$ with 8 dummy cycles
- $2 \mathrm{I} / \mathrm{O}: 80 \mathrm{MHz}$ with 4 dummy cycles, equivalent to 160 MHz
- 4 I/O: 70MHz with 6 dummy cycles, equivalent to 280 MHz ;
- Fast program time:
1.2ms (typ.)
and 3ms (max.)/page (256-byte per page)
- Byte program time: 10us (typ.)
- Fast erase time
- 30ms(typ.)
and 200ms(max.)/sector (4K-byte per sector)
- 200ms(typ.)
and 1000ms(max.)/block(32K-byte per block)
- 500ms(typ.)
and 2000ms(max.)/block(64K-byte per block)
- 2.5.s(typ.) and 5s(max.)/chip
- Low Power Consumption
- Low active read current:

12 mA (max.) at 80 MHz ,
7 mA (max.) at 33 MHz

- Low active erase/programming current: 25mA (max.)
- Low standby current: 8uA (typ.)/30uA (max.)
- Low Deep Power Down current: 8uA(max.)
- Typical 100,000 erase/program cycles
- 20 years data retention


## SOFTWARE FEATURES

- Input Data Format
- 1-byte Command code
- Advanced Security Features
- Block lock protection

The BP0-BP3 status bit defines the size of the area to be software protection against program and erase instructions

- Additional 4K-bit secured OTP for unique identifier
- Auto Erase and Auto Program Algorithm
- Automatically erases and verifies data at selected sector or block
- Automatically programs and verifies data at selected page by an internal algorithm that automatically times the program pulse widths (Any page to be programed should have page in the erased state first).
- Status Register Feature
- Electronic Identification
- JEDEC 1-byte manufacturer ID and 2-byte device ID
- RES command for 1-byte Device ID
- REMS, REMS2 and REMS4 commands for 1-byte manufacturer ID and 1-byte device ID
- Support Serial Flash Discoverable Parameters (SFDP) mode


## HARDWARE FEATURES

- SCLK Input
- Serial clock input
- SI/SIOO
- Serial Data Input or Serial Data Input/Output for $2 \times \mathrm{I} /$ O read mode and $4 \times \mathrm{l} / \mathrm{O}$ read mode
- SO/SIO1
- Serial Data Output or Serial Data Input/Output for 2 x

I/O read mode and $4 \times$ I/O read mode

- WP\#/SIO2
- Hardware write protection or serial data Input/Output for $4 \times$ I/O read mode
- HOLD\#/SIO3
- HOLD feature, to pause the device without deselecting the device or serial data Input/Output for $4 \times \mathrm{I} / \mathrm{O}$ read mode
- PACKAGE
- 8-pin SOP (150mil)
- 8-land USON (4x3mm)
- 8-land USON (4x4mm)
- 8-land WSON (6x5mm)
- 8-WLCSP
- All devices are RoHS Compliant and Halogen-free

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## 2. GENERAL DESCRIPTION

The MX25U4033E is $4,194,304$ bit Serial NOR Flash memory, which is configured as $1,048,576 \times 4$ internally. The MX25U4033E features a serial peripheral interface and software protocol allowing operation on a simple 4 -wire bus while it is in single I/O mode. The four bus signals are a clock input (SCLK), a serial data input (SI), a serial data output (SO) and a chip select (CS\#). Serial access to the device is enabled by CS\# input.

When it is in two I/O read mode, the SI pin and SO pin become SIOO pin and SIO1 pin for address/dummy bits input and data output. When it is in four I/O read mode, the SI pin, SO pin, WP\# pin and HOLD\# pin become SIOO pin, SIO1 pin, SIO2 pin and SIO3 pin for address/dummy bits input and data output.

The MX25U4033E MXSMIO ${ }^{\circledR}$ (Serial Multi I/O) provides sequential read operation on the whole chip.
After program/erase command is issued, auto program/erase algorithms which program/erase and verify the specified page or sector/block locations will be executed. Program command is executed on byte basis, or page (256 bytes) basis. Erase command is executed on 4 K -byte sector, 32K-byte block, or 64 K -byte block, or whole chip basis.

To provide user with ease of interface, a status register is included to indicate the status of the chip. The status read command can be issued to detect completion status of a program or erase operation via the WIP bit.
Advanced security features enhance the protection and security functions, please see security features section for more details.

When the device is not in operation and CS\# is high, it is put in standby mode.
The MX25U4033E utilizes Macronix's proprietary memory cell, which reliably stores memory contents even after 100,000 program and erase cycles.

Table 1. Additional Feature Comparison

|  | Protection and Security |  |  | Read Performance |  | Identifier |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Flexible Block Protection (BP0-BP3) | Individual Protect | $\begin{gathered} 4 \mathrm{~K} \text {-bit } \\ \text { secured OTP } \end{gathered}$ | 2 I/O Read | 4 I/O Read | RES <br> (Command: AB hex) | REMS/ REMS2/ REMS4 (Command: 90/EF/DF hex) | RDID (Command: 9F hex) |
| MX25U4033E | V | V | V | V | V | 33 (hex) | $\begin{gathered} \hline \text { C2 } 33 \text { (hex) } \\ \text { (if ADD }=0 \text { ) } \\ \hline \end{gathered}$ | $\begin{gathered} \hline \text { C2 } 2533 \\ \text { (hex) } \\ \hline \end{gathered}$ |

## 3. PIN CONFIGURATIONS

## 8-LAND USON( $4 \times 3 \mathrm{~mm}$ ), USON ( $4 \times 4 \mathrm{~mm}$ )



## 8-LAND WSON (6x5mm)



8-BALL BGA (WLCSP) TOP View

A

B

C

D


8-PIN SOP (150mil)


## 4. PIN DESCRIPTION

| SYMBOL | DESCRIPTION |
| :---: | :---: |
| CS\# | Chip Select |
| SI/SIOO | Serial Data Input (for $1 \times \mathrm{I} / \mathrm{O}$ )/ Serial Data Input \& Output (for 2xl/O or 4xl/ O read mode) |
| SO/SIO1 | Serial Data Output (for $1 \times \mathrm{I} / \mathrm{O}$ )/ Serial Data Input \& Output (for 2xI/O or 4xl/ O read mode) |
| SCLK | Clock Input |
| WP\#/SIO2 | Write Protection Active Low or Serial Data Input \& Output (for 4xI/O read mode) ${ }^{\text {Note } 1}$ |
| HOLD\#/SIO3 | To pause the device without deselecting the device ${ }^{\text {Note }}{ }^{1}$ or Serial Data Input \& Output (for 4xI/O read mode) |
| VCC | + 1.8V Power Supply |
| GND | Ground |

Note:

1. HOLD\# and WP\# with internal pull high circuit.

## 5. BLOCK DIAGRAM



* Depends on part number options.

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## 6. DATA PROTECTION

During power transition, there may be some false system level signals which result in inadvertent erasure or programming. The device is designed to protect itself from these accidental write cycles.

The state machine will be reset as standby mode automatically during power up. In addition, the control register architecture of the device constrains that the memory contents can only be changed after specific command sequences have completed successfully.

In the following, there are several features to protect the system from the accidental write cycles during VCC powerup and power-down or from system noise.

- Valid command length checking: The command length will be checked whether it is at byte base and completed on byte boundary.
- Write Enable (WREN) command: WREN command is required to set the Write Enable Latch bit (WEL) before issuing other commands to change data. The WEL bit will return to resetting stage while the following conditions occurred:
- Power-up
- Completion of Write Disable (WRDI) command
- Completion of Write Status Register (WRSR) command
- Completion of Page Program (PP) command
- Completion of Quad page program (4PP) command
- Completion of Sector Erase (SE) command
- Completion of Block Erase 32KB (BE32K) command
- Completion of Block Erase (BE) command
- Completion of Chip Erase (CE) command
- Completion of Write Protection Select (WPSEL) command
- Completion of Write Security Register (WRSCUR) command
- Completion of Single Block Lock/Unlock (SBLK/SBULK) command
- Completion of Gang Block Lock/Unlock (GBLK/GBULK) command
- Deep Power Down Mode: By entering deep power down mode, the flash device also is under protected from writing all commands except Release from deep power down mode command (RDP) and Read Electronic Signature command (RES).
- Advanced Security Features: there are some protection and security features which protect content from inadvertent write and hostile access.


## I. Block lock protection

- The Software Protected Mode (SPM) use (BP3, BP2, BP1, BP0) bits to allow part of memory to be protected as read only. The protected area definition is shown as table of "Table 2. Protected Area Sizes", the protected areas are more flexible which may protect various area by setting value of $\mathrm{BP} 0-\mathrm{BP} 3$ bits.
Please refer to table of "Table 2. Protected Area Sizes".
- The Hardware Protected Mode (HPM) use WP\#/SIO2 to protect the (BP3, BP2, BP1, BP0) bits and SRWD bit. If the system goes into four I/O read mode, the feature of HPM will be disabled.

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Table 2. Protected Area Sizes

| Status Bit |  |  |  | Protect Level |
| :---: | :---: | :---: | :---: | :--- |
| BP3 | BP2 | BP1 | BP0 |  |
| 0 | 0 | 0 | 0 | 0 (none) |
| 0 | 0 | 0 | 1 | 1 (1block, protected block 7th) |
| 0 | 0 | 1 | 0 | 2 (2blocks, protected block 6th~7th) |
| 0 | 0 | 1 | 1 | 3 (4blocks, protected block 4th~7th) |
| 0 | 1 | 0 | 0 | 4 (8blocks, protected all) |
| 0 | 1 | 0 | 1 | 5 (8blocks, protected all) |
| 0 | 1 | 1 | 0 | 6 (8blocks, protected all) |
| 0 | 1 | 1 | 1 | 7 (8blocks, protected all) |
| 1 | 0 | 0 | 0 | 8 (8blocks, protected all) |
| 1 | 0 | 0 | 1 | 9 (8blocks, protected all) |
| 1 | 0 | 1 | 0 | 10 (8blocks, protected all) |
| 1 | 0 | 1 | 1 | 11 (8blocks, protected all) |
| 1 | 1 | 0 | 0 | 12 (4blocks, protected block 0th~3rd) |
| 1 | 1 | 0 | 1 | 13 (6blocks, protected block 0th~5th) |
| 1 | 1 | 1 | 0 | 14 (7blocks, protected block 0th~6th) |
| 1 | 1 | 1 | 1 | 15 (8blocks, protected all) |

II. Additional 4K-bit secured OTP for unique identifier: to provide 4K-bit One-Time Program area for setting device unique serial number - Which may be set by factory or system maker. Please refer to "Table 3. 4K-bit Secured OTP Definition".

- Security register bit 0 indicates whether the secured OTP area is locked by factory or not.
- To program the 4K-bit secured OTP by entering 4K-bit secured OTP mode (with ENSO command), and going through normal program procedure, and then exiting 4K-bit secured OTP mode by writing EXSO command.
- Customer may lock-down the customer lockable secured OTP by writing WRSCUR(write security register) command to set customer lock-down bit1 as "1". Please refer to "Table 9. Security Register Definition" for security register bit definition and "Table 3. $4 K$-bit Secured OTP Definition" for address range definition.


## Note:

Once lock-down whatever by factory or customer, it cannot be changed any more. While in 4K-bit Secured OTP mode, array access is not allowed.

Table 3. 4K-bit Secured OTP Definition

| Address range | Size | Standard Factory Lock | Customer Lock |
| :---: | :---: | :---: | :---: |
| $x x \times 000 \sim x x \times 00 F$ | $128-$ bit | ESN (electrical serial number) | Determined by customer |
| $\mathrm{xxx010} \mathrm{\sim xxx1FF}$ | 3968 -bit | N/A |  |

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## 7. MEMORY ORGANIZATION

Table 4. Memory Organization

| Block (64KB) | Block <br> (32KB) | Sector (4KB) | Address Range |  | Individual Sector Lock/Unlock |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7 | $\begin{gathered} 15 \\ 1 \\ 14 \end{gathered}$ | 127 | 07F000h | 07FFFFh |  |
|  |  | : | : | : |  |
|  |  | 112 | 070000h | 070FFFh |  |
| 6 | $\begin{gathered} 13 \\ \mid \\ 12 \end{gathered}$ | 111 | 06F000h | 06FFFFh | Individual Block Lock/Unlock |
|  |  | : | : | : |  |
|  |  | 96 | 060000h | 060FFFh |  |
| 5 | $\begin{gathered} 11 \\ \text { \| } \\ 10 \end{gathered}$ | 95 | 05F000h | 05FFFFh |  |
|  |  | : | : | : |  |
|  |  | 80 | 050000h | 050FFFh |  |
| 4 | $\begin{aligned} & 9 \\ & 1 \\ & 8 \end{aligned}$ | 79 | 04F000h | 04FFFFh |  |
|  |  | : | : | : |  |
|  |  | 64 | 040000h | 040FFFh |  |
| 3 | $\begin{aligned} & \hline 7 \\ & 1 \\ & 6 \end{aligned}$ | 63 | 03F000h | 03FFFFh | $\downarrow$ |
|  |  | : | : | : |  |
|  |  | 48 | 030000h | 030FFFh |  |
| 2 | $\begin{aligned} & 5 \\ & 1 \\ & 4 \end{aligned}$ | 47 | 02F000h | 02FFFFh |  |
|  |  | : | : | : |  |
|  |  | 32 | 020000h | 020FFFh |  |
| 1 | $\begin{aligned} & 3 \\ & 1 \\ & 2 \end{aligned}$ | 31 | 01F000h | 01FFFFh |  |
|  |  | : | : | : |  |
|  |  | 16 | 010000h | 010FFFh |  |
| 0 | $\begin{aligned} & 1 \\ & 1 \\ & 0 \end{aligned}$ | 15 | 00F000h | 00FFFFh |  |
|  |  | : | : | : |  |
|  |  | 2 | 002000h | 002FFFh |  |
|  |  | 1 | 001000h | 001FFFh |  |
|  |  | 0 | 000000h | 000FFFh |  |

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## 8. DEVICE OPERATION

1. Before a command is issued, status register should be checked to ensure device is ready for the intended operation.
2. When incorrect command is inputted to this device, it enters standby mode and remains in standby mode until next CS\# falling edge. In standby mode, SO pin of the device is High-Z.
3. When correct command is inputted to this device, it enters active mode and remains in active mode until next CS\# rising edge.
4. Input data is latched on the rising edge of Serial Clock (SCLK) and data is shifted out on the falling edge of SCLK. The difference of Serial mode 0 and mode 3 is shown as "Figure 1. Serial Modes Supported".
5. For the following instructions: RDID, RDSR, RDSCUR, READ, FAST_READ, RDSFDP, 2READ, 4READ, RES, REMS, REMS2 and REMS4, the shifted-in instruction sequence is followed by a data-out sequence. After any bit of data being shifted out, the CS\# can be high. For the following instructions: WREN, WRDI, WRSR, SE, BE32K, BE, CE, PP, 4PP, RDP, DP, WPSEL, SBLK, SBULK, GBLK, GBULK,ENSO, EXSO, and WRSCUR, the CS\# must go high exactly at the byte boundary; otherwise, the instruction will be rejected and not executed.
6. While a Write Status Register, Program or Erase operation is in progress, access to the memory array is neglected and will not affect the current operation of WRSCUR, WPSEL Write Status Register, Program and Erase.

Figure 1. Serial Modes Supported


## Note:

CPOL indicates clock polarity of Serial master, CPOL=1 for SCLK high while idle, CPOL=0 for SCLK low while not transmitting. CPHA indicates clock phase. The combination of CPOL bit and CPHA bit decides which Serial mode is supported.

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## 9. HOLD FEATURE

HOLD\# pin signal goes low to hold any serial communications with the device. The HOLD feature will not stop the operation of write status register, programming, or erasing in progress.

The operation of HOLD requires Chip Select (CS\#) keeping low and starts on falling edge of HOLD\# pin signal while Serial Clock (SCLK) signal is being low (if Serial Clock signal is not being low, HOLD operation will not start until Serial Clock signal being low). The HOLD condition ends on the rising edge of HOLD\# pin signal while Serial Clock(SCLK) signal is being low (if Serial Clock signal is not being low, HOLD operation will not end until Serial Clock being low).

Figure 2. Hold Condition Operation


During the HOLD operation, the Serial Data Output (SO) is high impedance when Hold\# pin goes low and will keep high impedance until Hold\# pin goes high. The Serial Data Input (SI) is don't care if both Serial Clock (SCLK) and Hold\# pin goes low and will keep the state until SCLK goes low and Hold\# pin goes high. If Chip Select (CS\#) drives high during HOLD operation, it will reset the internal logic of the device. To re-start communication with chip, the HOLD\# must be at high and CS\# must be at low. (Note: The HOLD feature is disabled during Quad I/O mode.)

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## 10. COMMAND DESCRIPTION

Table 5. Command Set

## Read Commands

| I/O | 1 | 1 | 1 | 2 | 4 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Command <br> (byte) | READ <br> (normal read) | FAST READ <br> (fast read data) | RDSFDP <br> (Read SFDP) | 2READ <br> $(2 \times \mathrm{I} / \mathrm{O}$ read <br> command) | 4READ <br> $(4 \times \mathrm{I} / \mathrm{O}$ read <br> command) |
| Clock rate <br> (MHz) | 50 | 80 | 80 | 80 | 70 |
| 1st byte | 03 (hex) | 0B (hex) | 5 (hex) | BB (hex) | EB (hex) |
| 2nd byte | AD1 | AD1 | AD1 | AD1 | AD1 |
| 3rd byte | AD2 | AD2 | AD2 | AD2 | AD2 |
| 4th byte | AD3 | AD3 | AD3 | AD3 | AD3 |
| 5th byte |  | Dummy | Dummy | Dummy | Dummy |
|  | n bytes read <br> out until CS\# <br> goes high | n bytes read <br> out until CS\# <br> goes high | Read SFDP <br> mode | n bytes read <br> out by $2 \times \mathrm{I} / \mathrm{O}$ <br> until CS\# goes <br> high | n bytes read <br> out by 4 $\mathrm{l} / \mathrm{O}$ <br> until CS\# goes <br> high |
| Action |  |  |  |  |  |

## Program/Erase Commands

| Command <br> (byte) | WREN <br> (write enable) | WRDI <br> (write disable) | RDSR <br> (read status <br> register) | WRSR <br> (write status <br> register) | SE <br> (sector erase) | BE 32K <br> (block erase <br> 32 KB ) | BE <br> (block erase <br> 64KB) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1st byte | 06 (hex) | 04 (hex) | 05 (hex) | 01 (hex) | 20 (hex) | 52 (hex) | D8 (hex) |
| 2nd byte |  |  |  | Values | AD1 | AD1 | AD1 |
| 3rd byte |  |  |  | AD2 | AD2 | AD2 |  |
| 4th byte |  |  |  | AD3 | AD3 | AD3 |  |
| Action | sets the (WEL) <br> write enable <br> latch bit | resets the <br> (WEL) write <br> enable latch bit | to read out the <br> values of the <br> status register | to write new <br> values of the <br> status register | to erase the <br> selected sector | to erase the <br> selected 32KB <br> block | to erase the <br> selected block |


| Command <br> (byte) | CE <br> (chip erase) | PP <br> (page program) | 4PP <br> (Quad page <br> program) | DP <br> (Deep power <br> down) | RDP <br> (Release from <br> deep power <br> down) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1st byte | 60 or C7 (hex) | $02(\mathrm{hex})$ | $38(\mathrm{hex})$ | B9 (hex) | AB (hex) |
| 2nd byte |  | AD1 | AD1 |  |  |
| 3rd byte |  | AD2 | AD2 |  |  |
| 4th byte |  | AD3 | AD3 |  |  |
| Action | to erase whole <br> chip | to program the <br> selected page | quad input to <br> program the <br> selected page | enters deep <br> power down <br> mode | release from <br> deep power <br> down mode |

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## Security/ID/Mode Setting/Reset Commands

| Command (byte) | RDID (read identification) | RES (read electronic ID) | REMS (read electronic manufacturer \& device ID) | REMS2 (read electronic manufacturer \& device ID) | REMS4 (read electronic manufacturer \& device ID) | ENSO (enter secured OTP) | EXSO (exit secured OTP) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1st byte | 9F (hex) | AB (hex) | 90 (hex) | EF (hex) | DF (hex) | B1 (hex) | C1 (hex) |
| 2nd byte |  | x | x | X | x |  |  |
| 3rd byte |  | x | x | X | x |  |  |
| 4th byte |  | x | ADD(Note 1) | ADD | ADD |  |  |
| Action | outputs JEDEC <br> ID: 1-byte Manufacturer ID \& 2-byte Device ID | to read out 1-byte Device ID | output the Manufacturer ID \& Device ID | output the Manufacturer ID \& Device ID | output the Manufacturer ID \& Device ID | to enter the <br> 4K-bit secured OTP mode | to exit the <br> 4K-bit secured OTP mode |
| Command (byte) | RDSCUR (read security register) | WRSCUR (write security register) | SBLK (single block lock | SBULK (single block unlock) | RDBLOCK <br> (block protect <br> read) | GBLK (gang block lock) | GBULK (gang block unlock) |
| 1st byte | 2B (hex) | 2 F (hex) | 36 (hex) | 39 (hex) | 3C (hex) | 7E (hex) | 98 (hex) |
| 2nd byte |  |  | AD1 | AD1 | AD1 |  |  |
| 3rd byte |  |  | AD2 | AD2 | AD2 |  |  |
| 4th byte |  |  | AD3 | AD3 | AD3 |  |  |
| Action | to read value of security register | to set the lockdown bit as "1" (once lockdown, cannot be update) | individual block (64K-byte) or sector (4K-byte) write protect | individual block (64K-byte) or sector (4K-byte) unprotect | read individual block or sector write protect status | whole chip write protect | whole chip unprotect |


| Command <br> (byte) | WPSEL <br> (Write Protect <br> Selection) |
| :---: | :---: |
| 1st byte | 68 (hex) |
| 2nd byte |  |
| 3rd byte |  |
| 4th byte |  |
| Action | to enter and <br> enable individal <br> block protect <br> mode |

Note 1: ADD $=00 \mathrm{H}$ will output the manufacturer ID first and $\mathrm{ADD}=01 \mathrm{H}$ will output device ID first.
2: It is not recommended to adopt any other code not in the command definition table, which will potentially enter the hidden mode.

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## 10-1. Write Enable (WREN)

The Write Enable (WREN) instruction is for setting Write Enable Latch (WEL) bit. For those instructions like PP, 4PP, SE, BE32K, BE, CE, WPSEL, WRSCUR, SBLK, SBULK, GBLK, GBULK and WRSR, which are intended to change the device content WEL bit should be set every time after the WREN instruction setting the WEL bit.

The sequence of issuing WREN instruction is: CS\# goes low $\rightarrow$ sending WREN instruction code $\rightarrow$ CS\# goes high. (Please refer to "Figure 14. Write Enable (WREN) Sequence (Command 06)")

## 10-2. Write Disable (WRDI)

The Write Disable (WRDI) instruction is to reset Write Enable Latch (WEL) bit.
The sequence of issuing WRDI instruction is: CS\# goes low $\rightarrow$ sending WRDI instruction code $\rightarrow$ CS\# goes high.
(Please refer to "Figure 15. Write Disable (WRDI) Sequence (Command 04)")
The WEL bit is reset by following situations:

- Power-up
- Completion of Write Disable (WRDI) instruction
- Completion of Write Status Register (WRSR) instruction
- Completion of Page Program (PP) instruction
- Completion of Quad Page Program (4PP) instruction
- Completion of Sector Erase (SE) instruction
- Completion of Block Erase 32KB (BE32K) instruction
- Completion of Block Erase (BE) instruction
- Completion of Chip Erase (CE) instruction
- Completion of Write Protection Select (WPSEL) instruction
- Completion of Write Security Register (WRSCUR) instruction
- Completion of Single Block Lock/Unlock (SBLK/SBULK) instruction
- Completion of Gang Block Lock/Unlock (GBLK/GBULK) instruction


## 10-3. Read Identification (RDID)

The RDID instruction is to read the manufacturer ID of 1-byte and followed by Device ID of 2-byte. The MXIC Manufacturer ID is $C 2$ (hex), the memory type ID is 25(hex) as the first-byte device ID, and the individual device ID of second-byte ID are listed as table of "ID Definitions". (Please refer to "Table 8. ID Definitions")

The sequence of issuing RDID instruction is: CS\# goes low $\rightarrow$ sending RDID instruction code $\rightarrow 24$-bits ID data out on $\mathrm{SO} \rightarrow$ to end RDID operation can drive CS\# to high at any time during data out. (Please refer to "Figure 16. Read Identification (RDID) Sequence (Command 9F)")

While Program/Erase operation is in progress, it will not decode the RDID instruction, therefore there's no effect on the cycle of program/erase operation which is currently in progress. When CS\# goes high, the device is at standby stage.

## 10-4. Read Status Register (RDSR)

The RDSR instruction is for reading Status Register Bits. The Read Status Register can be read at any time (even in program/erase/WPSEL/WRSCUR/write status register condition). It is recommended to check the Write in Progress (WIP) bit before sending a new instruction when a program, erase, or write status register operation is in progress.

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The sequence of issuing RDSR instruction is: CS\# goes low $\rightarrow$ sending RDSR instruction code $\rightarrow$ Status Register data out on SO. (Please refer to "Figure 17. Read Status Register (RDSR) Sequence (Command 05)")

For user to check if Program/Erase operation is finished or not, RDSR instruction flow are shown as follows:

Program/Erase Flow with Read Array Data


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Program/Erase Flow without Read Array Data (read P_FAIL/E_FAIL flag)


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## WRSR Flow



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The definition of the status register bits is as below:
WIP bit. The Write in Progress (WIP) bit, a volatile bit, indicates whether the device is busy in program/erase/write status register progress. When WIP bit sets to 1, which means the device is busy in program/erase/write status register progress. When WIP bit sets to 0 , which means the device is not in progress of program/erase/write status register cycle.

WEL bit. The Write Enable Latch (WEL) bit is a volatile bit that is set to " 1 " by the WREN instruction. WEL needs to be set to " 1 " before the device can accept program and erase instructions, otherwise the program and erase instructions are ignored. WEL automatically clears to " 0 " when a program or erase operation completes. To ensure that both WIP and WEL are " 0 " and the device is ready for the next program or erase operation, it is recommended that WIP be confirmed to be " 0 " before checking that WEL is also " 0 ". If a program or erase instruction is applied to a protected memory area, the instruction will be ignored and WEL will clear to " 0 ".

BP3, BP2, BP1, BP0 bits. The Block Protect (BP3, BP2, BP1, BP0) bits, non-volatile bits, indicate the protected area (as defined in "Table 2. Protected Area Sizes") of the device to against the program/erase instruction without hardware protection mode being set. To write the Block Protect (BP3, BP2, BP1, BP0) bits requires the Write Status Register (WRSR) instruction to be executed. Those bits define the protected area of the memory to against Page Program (PP), Sector Erase (SE), Block Erase 32KB (BE32K), Block Erase (BE) and Chip Erase (CE) instructions (only if Block Protect bits (BP3:BP0) set to 0 , the CE instruction can be executed). The BP3, BP2, BP1, BP0 bits are " 0 " as default. Which is unprotected.

QE bit. The Quad Enable (QE) bit, non-volatile bit, while it is "0" (factory default), it performs non-Quad and WP\# is enabled. While QE is "1", it performs Quad I/O mode and WP\# is disabled. In the other word, if the system goes into four I/O mode (QE=1), the features of HPM and HOLD will be disabled.

SRWD bit. The Status Register Write Disable (SRWD) bit, non-volatile bit, is operated together with Write Protection (WP\#/SIO2) pin for providing hardware protection mode. The hardware protection mode requires SRWD sets to 1 and WP\#/SIO2 pin signal is low stage. In the hardware protection mode, the Write Status Register (WRSR) instruction is no longer accepted for execution and the SRWD bit and Block Protect bits (BP3, BP2, BP1, BPO) are read only. The SRWD bit defaults to be " 0 ".

Table 6. Status Register

| bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SRWD (status <br> register write <br> protect) | QE <br> (Quad <br> Enable) | BP3 <br> (level of <br> protected <br> block) | BP2 <br> (level of <br> protected <br> block) | BP1 <br> (level of <br> protected <br> block) | BP0 <br> (level of <br> protected <br> block) | WEL <br> (write enable <br> latch) | WIP <br> (write in <br> progress bit) |
| 1=status <br> register write <br> disabled <br> 0=status <br> register write <br> enabled | 1=Quad <br> Enable <br> E=not Quad <br> Enable | (note 1) | (note 1) | (note 1) | (note 1) | 1=write <br> enable <br> (=not write <br> enable | 1=write <br> operation <br> (not in write <br> operation |
| Non-volatile <br> bit | Non-volatile <br> bit | Non-volatile <br> bit | Non-volatile <br> bit | Non-volatile <br> bit | Non-volatile <br> bit | volatile bit | volatile bit |

Note 1: Please refer to the "Table 2. Protected Area Sizes".

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## 10-5. Write Status Register (WRSR)

The WRSR instruction is for changing the values of Status Register Bits. Before sending WRSR instruction, the Write Enable (WREN) instruction must be decoded and executed to set the Write Enable Latch (WEL) bit in advance. The WRSR instruction can change the value of Block Protect (BP3, BP2, BP1, BP0) bits to define the protected area of memory (as shown in "Table 2. Protected Area Sizes"). The WRSR also can set or reset the Quad enable (QE) bit and set or reset the Status Register Write Disable (SRWD) bit in accordance with Write Protection (WP\#/ SIO2) pin signal, but has no effect on bit1(WEL) and bit0 (WIP) of the status register. The WRSR instruction cannot be executed once the Hardware Protected Mode (HPM) is entered.

The sequence of issuing WRSR instruction is: CS\# goes low $\rightarrow$ sending WRSR instruction code $\rightarrow$ Status Register data on $\mathrm{SI} \rightarrow \mathrm{CS} \#$ goes high. (Please refer to "Figure 18. Write Status Register (WRSR) Sequence (Command 01)" )

The CS\# must go high exactly at the byte boundary; otherwise, the instruction will be rejected and not executed. The self-timed Write Status Register cycle time (tW) is initiated as soon as Chip Select (CS\#) goes high. The Write in Progress (WIP) bit still can be check out during the Write Status Register cycle is in progress. The WIP sets 1 during the tW timing, and sets 0 when Write Status Register Cycle is completed, and the Write Enable Latch (WEL) bit is reset.

## Table 7. Protection Modes

| Mode | Status register condition | WP\# and SRWD bit status | Memory |
| :---: | :---: | :---: | :---: |
| Software protection <br> mode (SPM) | Status register can be written <br> in (WEL bit is set to "1") and <br> the SRWD, BP0-BP3 <br> bits can be changed | WP\#=1 and SRWD bit=0, or <br> WP\#=0 and SRWD bit=0, or <br> WP\# | The protected area <br> cannot <br> be program or erase. |
| Hardware protection <br> mode (HPM) | The SRWD, BPo-BP3 of <br> status register bits cannot be <br> changed | WP\#=0, SRWD bit=1 | The protected area <br> cannot <br> be program or erase. |

## Note:

1. As defined by the values in the Block Protect (BP3, BP2, BP1, BPO) bits of the Status Register, as shown in "Table 2. Protected Area Sizes".

As the above table showing, the summary of the Software Protected Mode (SPM) and Hardware Protected Mode (HPM).
Software Protected Mode (SPM):

- When SRWD bit=0, no matter WP\#/SIO2 is low or high, the WREN instruction may set the WEL bit and can change the values of SRWD, BP3, BP2, BP1, BP0. The protected area, which is defined by BP3, BP2, BP1, BPO , is at software protected mode (SPM).
- When SRWD bit=1 and WP\#/SIO2 is high, the WREN instruction may set the WEL bit can change the values of SRWD, BP3, BP2, BP1, BP0. The protected area, which is defined by BP3, BP2, BP1, BP0, is at software protected mode (SPM)


## Note:

If SRWD bit=1 but WP\#/SIO2 is low, it is impossible to write the Status Register even if the WEL bit has previously been set. It is rejected to write the Status Register and not be executed.

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Hardware Protected Mode (HPM):

- When SRWD bit=1, and then WP\#/SIO2 is low (or WP\#/SIO2 is low before SRWD bit=1), it enters the hardware protected mode (HPM). The data of the protected area is protected by software protected mode by BP3, BP2, BP1, BP0 and hardware protected mode by the WP\#/SIO2 to against data modification.


## Note:

To exit the hardware protected mode requires WP\#/SIO2 driving high once the hardware protected mode is entered. If the WP\#/SIO2 pin is permanently connected to high, the hardware protected mode can never be entered; only can use software protected mode via BP3, BP2, BP1, BP0.
If the system enter Quad I/O QE=1, the feature of HPM will be disabled.

## 10-6. Read Data Bytes (READ)

The read instruction is for reading data out. The address is latched on rising edge of SCLK, and data shifts out on the falling edge of SCLK at a maximum frequency fR. The first address byte can be at any location. The address is automatically increased to the next higher address after each byte data is shifted out, so the whole memory can be read out at a single READ instruction. The address counter rolls over to 0 when the highest address has been reached.

The sequence of issuing READ instruction is: CS\# goes low $\rightarrow$ sending READ instruction code $\rightarrow 3$-byte address on $\mathrm{SI} \rightarrow$ data out on SO $\rightarrow$ to end READ operation can use CS\# to high at any time during data out. (Please refer to "Figure 19. Read Data Bytes (READ) Sequence (Command 03) (50MHz)")

## 10-7. Read Data Bytes at Higher Speed (FAST_READ)

The FAST_READ instruction is for quickly reading data out. The address is latched on rising edge of SCLK, and data of each bit shifts out on the falling edge of SCLK at a maximum frequency fC . The first address byte can be at any location. The address is automatically increased to the next higher address after each byte data is shifted out, so the whole memory can be read out at a single FAST_READ instruction. The address counter rolls over to 0 when the highest address has been reached.

The sequence of issuing FAST_READ instruction is: CS\# goes low $\rightarrow$ sending FAST_READ instruction code $\rightarrow$ 3 -byte address on $\mathrm{SI} \rightarrow 1$-dummy byte (default) address on $\mathrm{SI} \rightarrow$ data out on $\mathrm{SO} \rightarrow$ to end FAST_READ operation can use CS\# to high at any time during data out. (Please refer to "Figure 20. Read at Higher Speed (FAST_READ) Sequence (Command 0B)")

While Program/Erase/Write Status Register cycle is in progress, FAST_READ instruction is rejected without any impact on the Program/Erase/Write Status Register current cycle.

## 10-8. $2 \times \mathrm{I} / \mathrm{O}$ Read Mode (2READ)

The 2READ instruction enable double throughput of Serial NOR Flash in read mode. The address is latched on rising edge of SCLK, and data of every two bits (interleave on $2 \mathrm{I} / \mathrm{O}$ pins) shift out on the falling edge of SCLK at a maximum frequency fT . The first address byte can be at any location. The address is automatically increased to the next higher address after each byte data is shifted out, so the whole memory can be read out at a single 2READ instruction. The address counter rolls over to 0 when the highest address has been reached. Once writing 2READ instruction, the following address/dummy/data out will perform as 2-bit instead of previous 1-bit.

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The sequence of issuing 2READ instruction is: CS\# goes low $\rightarrow$ sending 2READ instruction $\rightarrow$ 24-bit address interleave on $\mathrm{SIO} 1 \& \mathrm{SIO} \rightarrow 4$ dummy cycles on $\mathrm{SIO} 1 \& \mathrm{SIO} \rightarrow$ data out interleave on $\mathrm{SIO} 1 \& \mathrm{SIO} \rightarrow$ to end 2READ operation can use CS\# to high at any time during data out (Please refer to "Figure 21. 2 x I/O Read Mode Sequence (Command BB)").

While Program/Erase/Write Status Register cycle is in progress, 2READ instruction is rejected without any impact on the Program/Erase/Write Status Register current cycle.

## 10-9. $4 \times$ I/O Read Mode (4READ)

The 4READ instruction enable quad throughput of Serial NOR Flash in read mode. A Quad Enable (QE) bit of status Register must be set to "1" before sending the 4READ instruction. The address is latched on rising edge of SCLK, and data of every four bits (interleave on 4 I/O pins) shift out on the falling edge of SCLK at a maximum frequency fQ . The first address byte can be at any location. The address is automatically increased to the next higher address after each byte data is shifted out, so the whole memory can be read out at a single 4READ instruction. The address counter rolls over to 0 when the highest address has been reached. Once writing 4READ instruction, the following address/dummy/data out will perform as 4-bit instead of previous 1-bit.

The sequence of issuing 4READ instruction is: CS\# goes low $\rightarrow$ sending 4READ instruction $\rightarrow 24$-bit address interleave on $\mathrm{SIO} 3, \mathrm{SIO} 2, \mathrm{SIO} 1 \& \mathrm{SIO} \rightarrow 2+4$ dummy cycles $\rightarrow$ data out interleave on $\mathrm{SIO} 3, \mathrm{SIO} 2, \mathrm{SIO} 1 \& \mathrm{SIO} 0 \rightarrow$ to end 4READ operation can use CS\# to high at any time during data out. (Please refer to "Figure 22. $4 \times 1 / O$ Read Mode Sequence (Command EB)")

While Program/Erase/Write Status Register cycle is in progress, 4READ instruction is rejected without any impact on the Program/Erase/Write Status Register current cycle.

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## 10-10. Performance Enhance Mode

The device could waive the command cycle bits if the two cycle bits after address cycle toggles. (Please note "Figure $22.4 \times$ I/O Read Mode Sequence (Command EB)")

After entering enhance mode, following CS\# go high, the device will stay in the read mode and treat CS\# go low of the first clock as address instead of command cycle.

Another sequence of issuing 4READ instruction especially useful in random access is: CS\# goes low $\rightarrow$ sending 4 READ instruction $\rightarrow$ 3-bytes address interleave on SIO3, SIO2, SIO1 \& SIOO $\rightarrow$ performance enhance toggling bit $\mathrm{P}[7: 0] \rightarrow 4$ dummy cycles $\rightarrow$ data out still CS\# goes high $\rightarrow$ CS\# goes low (reduce 4Read instruction) $\rightarrow 24$-bit random access address (Please refer to "Figure 23. $4 \times$ I/O Read Enhance Performance Mode Sequence (Command $E B)^{\prime \prime}$ ).

In the performance-enhancing mode, $\mathrm{P}[7: 4]$ must be toggling with $\mathrm{P}[3: 0]$; likewise $\mathrm{P}[7: 0]=\mathrm{A} 5 \mathrm{~h}, 5 \mathrm{Ah}$, F0h or 0 Fh can make this mode continue and reduce the next 4READ instruction. Once $P[7: 4]$ is no longer toggling with $P[3: 0]$; likewise $\mathrm{P}[7: 0]=\mathrm{FFh}, 00 \mathrm{~h}, \mathrm{AAh}$ or 55 h and afterwards CS\# is raised and then lowered, the system then will escape from performance enhance mode and return to normal operation.

## 10-11. Sector Erase (SE)

The Sector Erase (SE) instruction is for erasing the data of the chosen sector to be "1". The instruction is used for any 4K-byte sector. A Write Enable (WREN) instruction must execute to set the Write Enable Latch (WEL) bit before sending the Sector Erase (SE). Any address of the sector (see "Table 4. Memory Organization") is a valid address for Sector Erase (SE) instruction. The CS\# must go high exactly at the byte boundary (the least significant bit of the address been latched-in); otherwise, the instruction will be rejected and not executed.

Address bits [Am-A12] (Am is the most significant address) select the sector address.
The sequence of issuing SE instruction is: CS\# goes low $\rightarrow$ sending SE instruction code $\rightarrow$ 3-byte address on $\mathrm{SI} \rightarrow$ CS\# goes high. (Please refer to "Figure 26. Sector Erase (SE) Sequence (Command 20)")

The self-timed Sector Erase Cycle time (tSE) is initiated as soon as Chip Select (CS\#) goes high. The Write in Progress (WIP) bit still can be checked while the Sector Erase cycle is in progress. The WIP sets during the tSE timing, and clears when Sector Erase Cycle is completed, and the Write Enable Latch (WEL) bit is cleared. If the sector is protected by BP3 ~ 0 (WPSEL=0) or by individual lock (WPSEL=1), the Sector Erase (SE) instruction will not be executed on the sector.

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## 10-12. Block Erase (BE32K)

The Block Erase (BE32K) instruction is for erasing the data of the chosen block to be "1". The instruction is used for 32K-byte block erase operation. A Write Enable (WREN) instruction must be executed to set the Write Enable Latch (WEL) bit before sending the Block Erase (BE32K). Any address of the block (see "Table 4. Memory Organization") is a valid address for Block Erase (BE32K) instruction. The CS\# must go high exactly at the byte boundary (the least significant bit of address byte been latched-in); otherwise, the instruction will be rejected and not executed.

The sequence of issuing BE32K instruction is: CS\# goes low $\rightarrow$ sending BE32K instruction code $\rightarrow 3$-byte address on $\mathrm{SI} \rightarrow \mathrm{CS} \#$ goes high. (Please refer to "Figure 27. Block Erase 32KB (BE32K) Sequence (Command 52)")

The self-timed Block Erase Cycle time (tBE32K) is initiated as soon as Chip Select (CS\#) goes high. The Write in Progress (WIP) bit still can be checked while he Block Erase cycle is in progress. The WIP sets during the tBE32K timing, and clears when Block Erase Cycle is completed, and the Write Enable Latch (WEL) bit is cleared. If the block is protected by BP3 ~ 0 (WPSEL=0) or by individual lock (WPSEL=1), the Block Erase (tBE32K) instruction will not be executed on the block.

## 10-13. Block Erase (BE)

The Block Erase (BE) instruction is for erasing the data of the chosen block to be "1". The instruction is used for 64K-byte block erase operation. A Write Enable (WREN) instruction must be executed to set the Write Enable Latch (WEL) bit before sending the Block Erase (BE). Any address of the block (Please refer to "Table 4. Memory Organization") is a valid address for Block Erase (BE) instruction. The CS\# must go high exactly at the byte boundary (the least significant bit of address byte been latched-in); otherwise, the instruction will be rejected and not executed.

The sequence of issuing BE instruction is: $\mathrm{CS} \#$ goes low $\rightarrow$ sending BE instruction code $\rightarrow$ 3-byte address on $\mathrm{SI} \rightarrow$ CS\# goes high. (Please refer to "Figure 28. Block Erase (BE) Sequence (Command D8)")

The self-timed Block Erase Cycle time (tBE) is initiated as soon as Chip Select (CS\#) goes high. The Write in Progress (WIP) bit still can be checked while the Block Erase cycle is in progress. The WIP sets during the tBE timing, and clears when Block Erase Cycle is completed, and the Write Enable Latch (WEL) bit is cleared. If the block is protected by BP3 ~ 0 (WPSEL=0) or by individual lock (WPSEL=1), the Block Erase (BE) instruction will not be executed on the block.

## 10-14. Chip Erase (CE)

The Chip Erase (CE) instruction is for erasing the data of the whole chip to be "1". A Write Enable (WREN) instruction must be executed to set the Write Enable Latch (WEL) bit before sending the Chip Erase (CE). The CS\# must go high exactly at the byte boundary, otherwise the instruction will be rejected and not executed.

The sequence of issuing CE instruction is: CS\# goes low $\rightarrow$ sending CE instruction code $\rightarrow$ CS\# goes high. (Please refer to "Figure 29. Chip Erase (CE) Sequence (Command 60 or C7)")

The self-timed Chip Erase Cycle time (tCE) is initiated as soon as Chip Select (CS\#) goes high. The Write in Progress (WIP) bit still can be checked while the Chip Erase cycle is in progress. The WIP sets during the tCE timing, and clears when Chip Erase Cycle is completed, and the Write Enable Latch (WEL) bit is cleared. If the chip is protected by BP3 $\sim 0(W P S E L=0)$ or by individual lock (WPSEL=1), the Chip Erase (CE) instruction will not be executed. It will be only executed when BP3, BP2, BP1, BP0 all set to " 0 ".

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## 10-15. Page Program (PP)

The Page Program (PP) instruction is for programming the memory to be " 0 ". A Write Enable (WREN) instruction must be executed to set the Write Enable Latch (WEL) bit before sending the Page Program (PP). The device programs only the last 256 data bytes sent to the device. If the entire 256 data bytes are going to be programmed, A7A0 (the eight least significant address bits) should be cleared. The last address byte (the 8 least significant address bits, A7-A0) should be set to 0 for 256 bytes page program. If A7-A0 are not all zero, transmitted data that exceed page length are programmed from the starting address (24-bit address that last 8 bit are all 0 ) of currently selected page. If the data bytes sent to the device exceeds 256 , the last 256 data byte is programmed at the request page and previous data will be disregarded. If the data bytes sent to the device has not exceeded 256 , the data will be programmed at the request address of the page. There will be no effort on the other data bytes of the same page.

The sequence of issuing PP instruction is: CS\# goes low $\rightarrow$ sending PP instruction code $\rightarrow$ 3-byte address on $\mathrm{SI} \rightarrow$ at least 1-byte on data on $\mathrm{SI} \rightarrow \mathrm{CS} \mathrm{\#}$ goes high. (Please refer to "Figure 24. Page Program (PP) Sequence (Command 02)")

The CS\# must be kept to low during the whole Page Program cycle; The CS\# must go high exactly at the byte boundary (the latest eighth bit of data being latched in), otherwise the instruction will be rejected and will not be executed.

The self-timed Page Program Cycle time (tPP) is initiated as soon as Chip Select (CS\#) goes high. The Write in Progress (WIP) bit still can be checked while the Page Program cycle is in progress. The WIP sets during the tPP timing, and clears when Page Program Cycle is completed, and the Write Enable Latch (WEL) bit is cleared. If the page is protected by BP3 $\sim 0(W P S E L=0)$ or by individual lock (WPSEL=1), the Page Program (PP) instruction will not be executed.

## 10-16. 4 x I/O Page Program (4PP)

The Quad Page Program (4PP) instruction is for programming the memory to be "0". A Write Enable (WREN) instruction must be executed to set the Write Enable Latch (WEL) bit and Quad Enable (QE) bit must be set to "1" before sending the Quad Page Program (4PP). The Quad Page Programming takes four pins: SIO0, SIO1, SIO2, and SIO3 as address and data input, which can improve programmer performance and the effectiveness of application of lower clock less than 70 MHz . For system with faster clock, the Quad page program cannot provide more performance, because the required internal page program time is far more than the time data flows in. Therefore, we suggest that while executing this command (especially during sending data), user can slow the clock speed down to 70 MHz below. The other function descriptions are as same as standard page program.

The sequence of issuing 4PP instruction is: CS\# goes low $\rightarrow$ sending 4PP instruction code $\rightarrow 3$-byte address on $\mathrm{SIO}[3: 0] \rightarrow$ at least 1-byte on data on $\mathrm{SIO}[3: 0] \rightarrow \mathrm{CS} \mathrm{\#}$ goes high. (Please refer to "Figure $25.4 \times \mathrm{l} / \mathrm{O}$ Page Program (4PP) Sequence (Command 38)")

If the page protected by BP3 $\sim 0$ (WPSEL=0) or by individual lock (WPSEL=1), the Quad page program (4PP) instruction will not be executed.

## 10-17. Deep Power-down (DP)

The Deep Power-down (DP) instruction is for setting the device to minimize the power consumption (the standby current is reduced from ISB1 to ISB2). The Deep Power-down mode requires the Deep Power-down (DP) instruction to enter, during the Deep Power-down mode, the device is not active and all Write/Program/Erase instruction are ignored.

The sequence of issuing DP instruction is: CS\# goes low $\rightarrow$ sending DP instruction code $\rightarrow$ CS\# goes high.
(Please refer to "Figure 30. Deep Power-down (DP) Sequence (Command B9)")

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Once the DP instruction is set, all instruction will be ignored except the Release from Deep Power-down mode (RDP) and Read Electronic Signature (RES) instruction. (Those instructions allow the ID being reading out). When Powerdown, or software reset command the deep power-down mode automatically stops, and when power-up, the device automatically is in standby mode. For DP instruction the CS\# must go high exactly at the byte boundary (the latest eighth bit of instruction code been latched-in); otherwise, the instruction will not executed. As soon as Chip Select (CS\#) goes high, a delay of tDP is required before entering the Deep Power-down mode.

## 10-18. Release from Deep Power-down (RDP), Read Electronic Signature (RES)

The Release from Deep Power-down (RDP) instruction is completed by driving Chip Select (CS\#) High. When Chip Select (CS\#) is driven High, the device is put in the Stand-by Power mode. If the device was not previously in the Deep Power-down mode, the transition to the Stand-by Power mode is immediate. If the device was previously in the Deep Power-down mode, though, the transition to the Stand-by Power mode is delayed by tRES2, and Chip Select (CS\#) must remain High for at least tRES2(max), as specified in "Table 14. AC Characteristics". AC Characteristics. Once in the Stand-by Power mode, the device waits to be selected, so that it can receive, decode and execute instructions. The RDP instruction is only for releasing from Deep Power Down Mode.

RES instruction is for reading out the old style of 8-bit Electronic Signature, whose values are shown as "Table 8. ID Definitions" on next page. This is not the same as RDID instruction. It is not recommended to use for new design. For new design, please use RDID instruction.

The sequence is shown as "Figure 31. RDP and Read Electronic Signature (RES) Sequence (Command $A B$ )" and "Figure 32. Release from Deep Power-down (RDP) Sequence (Command AB)". Even in Deep power-down mode, the RDP and RES are also allowed to be executed, only except the device is in progress of program/erase/write cycle; there's no effect on the current program/erase/write cycle in progress.

The RES instruction is ended by CS\# goes high after the ID been read out at least once. The ID outputs repeatedly if continuously send the additional clock cycles on SCLK while CS\# is at low. If the device was not previously in Deep Power-down mode, the device transition to standby mode is immediate. If the device was previously in Deep Power-down mode, there's a delay of tRES2 to transit to standby mode, and CS\# must remain to high at least tRES2(max). Once in the standby mode, the device waits to be selected, so it can be receive, decode, and execute instruction.

## 10-19. Read Electronic Manufacturer ID \& Device ID (REMS), (REMS2), (REMS4)

The REMS, REMS2 and REMS4 instruction provides both the JEDEC assigned Manufacturer ID and the specific Device ID.
The instruction is initiated by driving the CS\# pin low and shift the instruction code "90h", "DFh" or "EFh" followed by two dummy bytes and one bytes address (A7~A0). After which, the Manufacturer ID for MXIC (C2h) and the Device ID are shifted out on the falling edge of SCLK with most significant bit (MSB) first as shown in "Figure 33. Read Electronic Manufacturer \& Device ID (REMS) Sequence (Command 90/EF/DF)". The Device ID values are listed in "Table 8. ID Definitions". If the one-byte address is initially set to 01 h , then the Device ID will be read first and then followed by the Manufacturer ID. The Manufacturer and Device IDs can be read continuously, alternating from one to the other. The instruction is completed by driving CS\# high.

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Table 8. ID Definitions

| Command Type | MX25U4033E |  |  |
| :---: | :---: | :---: | :---: |
| RDID (JEDEC ID) | manufacturer ID | memory type | memory density |
|  | C2 | 25 | 33 |
| RES | electronic ID |  |  |
|  |  | 33 |  |
| REMS/REMS2/REMS4 | manufacturer ID | device ID |  |
|  | C2 | 33 |  |

## 10-20. Enter Secured OTP (ENSO)

The ENSO instruction is for entering the additional 4K-bit secured OTP mode. While device is in 4 K -bit secured OTP mode, main array access is not available. The additional 4K-bit secured OTP is independent from main array, and may be used to store unique serial number for system identifier. After entering the Secured OTP mode, follow standard read or program procedure to read out the data or update data. The Secured OTP data cannot be updated again once it is lock-down.

The sequence of issuing ENSO instruction is: CS\# goes low $\rightarrow$ sending ENSO instruction to enter Secured OTP mode $\rightarrow$ CS\# goes high.

Please note that WRSR/WRSCUR/WPSEL commands are not acceptable during the access of secure OTP region, once security OTP is lock down, only read related commands are valid.

## 10-21. Exit Secured OTP (EXSO)

The EXSO instruction is for exiting the additional 4K-bit secured OTP mode.
The sequence of issuing EXSO instruction is: CS\# goes low $\rightarrow$ sending EXSO instruction to exit Secured OTP mode $\rightarrow$ CS\# goes high.

## 10-22. Read Security Register (RDSCUR)

The RDSCUR instruction is for reading the value of Security Register bits. The Read Security Register can be read at any time (even in program/erase/write status register/write security register condition) and continuously.

The sequence of issuing RDSCUR instruction is: CS\# goes low $\rightarrow$ sending RDSCUR instruction $\rightarrow$ Security Register data out on SO $\rightarrow$ CS\# goes high. (Please see "Figure 34. Read Security Register (RDSCUR) Sequence (Command 2B)")

The definition of the Security Register bits is as below:
Secured OTP Indicator bit. The Secured OTP indicator bit shows the chip is locked by factory or not. When it is " 0 ", it indicates non-factory lock; "1" indicates factory-lock.

Lock-down Secured OTP (LDSO) bit. By writing WRSCUR instruction, the LDSO bit may be set to "1" for customer lock-down purpose. However, once the bit is set to "1" (lock-down), the LDSO bit and the 4K-bit Secured OTP area cannot be updated any more.

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Table 9. Security Register Definition

| Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| WPSEL | E_FAIL | P_FAIL | Reserved | Reserved | Reserved | LDSO <br> (indicate if <br> lock-down) | Secured OTP <br> indicator bit |
| $0=$ normal <br> WP mode <br> $1=$ individual <br> mode <br> (default=0) | $0=$ normal <br> Erase <br> succeed <br> Eindividual <br> Erase failed <br> (default=0) | 0=normal <br> Program <br> succeed <br> (=indicate <br> Program <br> failed <br> (default=0) | - | - |  |  |  |
| (dot lock- |  |  |  |  |  |  |  |
| down |  |  |  |  |  |  |  |
| dock-down | $0=$ non- <br> factory <br> lock <br> (cannot <br> logram/ <br> erase <br> OTP) | $1=$ factory <br> lock |  |  |  |  |  |
| Non-volatile <br> bit (OTP) | Volatile bit | Volatile bit | Volatile bit | Volatile bit | Volatile bit | Non-volatile <br> bit <br> (OTP) | Non-volatile <br> bit (OTP) |

## 10-23. Write Security Register (WRSCUR)

The WRSCUR instruction is for setting the values of Security Register Bits. The WREN (Write Enable) instruction is required before issuing WRSCUR instruction. The WRSCUR instruction may change the values of bit1 (LDSO bit) for customer to lock-down the 4K-bit Secured OTP area. Once the LDSO bit is set to "1", the Secured OTP area cannot be updated any more. The LDSO bit is an OTP bit. Once the LDSO bit is set, the value of LDSO bit can not be altered any more.

The sequence of issuing WRSCUR instruction is :CS\# goes low $\rightarrow$ sending WRSCUR instruction $\rightarrow$ CS\# goes high. (Please see "Figure 35. Write Security Register (WRSCUR) Sequence (Command 2F)".)

The CS\# must go high exactly at the boundary; otherwise, the instruction will be rejected and not executed.

## 10-24. Write Protection Selection (WPSEL)

When the system accepts and executes WPSEL instruction, bit 7 in the security register will be set. The WREN (Write Enable) instruction is required before issuing WPSEL instruction. It will activate SBLK, SBULK, RDBLOCK, GBLK, GBULK etc instructions to conduct block lock protection and replace the original Software Protect Mode (SPM) use (BP3~BPO) indicated block methods.

The sequence of issuing WPSEL instruction is: CS\# goes low $\rightarrow$ sending WPSEL instruction to enter the individual block protect mode $\rightarrow$ CS\# goes high.

Every time after the system is powered-on, the Security Register bit 7 is checked. If WPSEL=1, then all the blocks and sectors will be write-protected by default. User may only unlock the blocks or sectors via SBULK and GBULK instructions. Program or erase functions can only be operated after the Unlock instruction is executed.

Once WPSEL is set, it cannot be changed.

WPSEL instruction function flow is as follows:

Figure 3. WPSEL Flow


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## 10-25. Single Block Lock/Unlock Protection (SBLK/SBULK)

These instructions are only effective after WPSEL was executed. The SBLK instruction is for write protection a specified block (or sector) of memory, using $\mathrm{A}_{\text {max }}-\mathrm{A} 16$ or ( $\mathrm{A}_{\text {max }}-\mathrm{A} 12$ ) address bits to assign a 64 Kbyte block (or 4 K bytes sector) to be protected as read only. The SBULK instruction will cancel the block (or sector) write protection state. This feature allows user to stop protecting the entire block (or sector) through the chip unprotect command (GBULK).

The WREN (Write Enable) instruction is required before issuing SBLK/SBULK instruction.
The sequence of issuing SBLK/SBULK instruction is: CS\# goes low $\rightarrow$ send SBLK/SBULK (36h/39h) instruction $\rightarrow$ send 3 address bytes assign one block (or sector) to be protected on SI pin $\rightarrow$ CS\# goes high. The CS\# must go high exactly at the byte boundary, otherwise the instruction will be rejected and not be executed.

SBLK/SBULK instruction function flow is as follows:

Figure 4. Block Lock Flow


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Figure 5. Block Unlock Flow


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## 10-26. Read Block Lock Status (RDBLOCK)

This instruction is only effective after WPSEL was executed. The RDBLOCK instruction is for reading the status of protection lock of a specified block (or sector), using $\mathrm{A}_{\text {MAX }}-\mathrm{A} 16$ (or $\mathrm{A}_{\text {MAX }}-\mathrm{A} 12$ ) address bits to assign a 64 K bytes block ( 4 K bytes sector) and read protection lock status bit which the first byte of Read-out cycle. The status bit is"1" to indicate that this block has be protected, that user can read only but cannot write/program /erase this block. The status bit is " 0 " to indicate that this block hasn't be protected, and user can read and write this block.

The sequence of issuing RDBLOCK instruction is: CS\# goes low $\rightarrow$ send RDBLOCK (3Ch) instruction $\rightarrow$ send 3 address bytes to assign one block on SI pin $\rightarrow$ read block's protection lock status bit on SO pin $\rightarrow$ CS\# goes high.

## 10-27. Gang Block Lock/Unlock (GBLK/GBULK)

These instructions are only effective after WPSEL was executed. The GBLK/GBULK instruction is for enable/disable the lock protection block of the whole chip.

The WREN (Write Enable) instruction is required before issuing GBLK/GBULK instruction.
The sequence of issuing GBLK/GBULK instruction is: CS\# goes low $\rightarrow$ send GBLK/GBULK (7Eh/98h) instruction $\rightarrow$ CS\# goes high.

The CS\# must go high exactly at the byte boundary, otherwise, the instruction will be rejected and not be executed.

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## 10-28. Read SFDP Mode (RDSFDP)

The Serial Flash Discoverable Parameter (SFDP) standard provides a consistent method of describing the functional and feature capabilities of serial flash devices in a standard set of internal parameter tables. These parameter tables can be interrogated by host system software to enable adjustments needed to accommodate divergent features from multiple vendors. The concept is similar to the one found in the Introduction of JEDEC Standard, JESD68 on CFI.

The sequence of issuing RDSFDP instruction is CS\# goes low $\rightarrow$ send RDSFDP instruction (5Ah) $\rightarrow$ send 3 address bytes on SI pin $\rightarrow$ send 1 dummy byte on SI pin $\rightarrow$ read SFDP code on SO $\rightarrow$ to end RDSFDP operation can use CS\# to high at any time during data out.

SFDP is a standard of JEDEC. JESD216. v1.0.
Figure 6. Read Serial Flash Discoverable Parameter (RDSFDP) Sequence


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Table 10. Signature and Parameter Identification Data Values
SFDP Table (JESD216) below is for MX25U4033EBAI-12G, MX25U4033EM1I-12G, MX25U4033EZNI-12G, MX25U4033EZUI-12G and MX25U4033EZBI-12G

| Description | Comment | Add (h) (Byte) | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { DW Add } \\ (\mathrm{Bit}) \end{array} \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { Data (h/b) } \\ \text { (Note1) } \end{array} \\ \hline \end{array}$ | Data <br> (h) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| SFDP Signature | Fixed: 50444653h | 00h | 07:00 | 53h | 53h |
|  |  | 01h | 15:08 | 46h | 46h |
|  |  | 02h | 23:16 | 44h | 44h |
|  |  | 03h | 31:24 | 50h | 50h |
| SFDP Minor Revision Number | Start from 00h | 04h | 07:00 | 00h | 00h |
| SFDP Major Revision Number | Start from 01h | 05h | 15:08 | 01h | 01h |
| Number of Parameter Headers | This number is 0 -based. Therefore, 0 indicates 1 parameter header. | 06h | 23:16 | 01h | 01h |
| Unused |  | 07h | 31:24 | FFh | FFh |
| ID number (JEDEC) | 00h: it indicates a JEDEC specified header. | 08h | 07:00 | 00h | 00h |
| Parameter Table Minor Revision Number | Start from 00h | 09h | 15:08 | 00h | 00h |
| Parameter Table Major Revision Number | Start from 01h | OAh | 23:16 | 01h | 01h |
| Parameter Table Length (in double word) | How many DWORDs in the Parameter table | OBh | 31:24 | 09h | 09h |
| Parameter Table Pointer (PTP) | First address of JEDEC Flash Parameter table | 0Ch | 07:00 | 30h | 30h |
|  |  | 0Dh | 15:08 | 00h | 00h |
|  |  | 0Eh | 23:16 | 00h | 00h |
| Unused |  | 0Fh | 31:24 | FFh | FFh |
| ID number (Macronix manufacturer ID) | it indicates Macronix manufacturer ID | 10h | 07:00 | C2h | C2h |
| Parameter Table Minor Revision Number | Start from 00h | 11h | 15:08 | 00h | 00h |
| Parameter Table Major Revision Number | Start from 01h | 12h | 23:16 | 01h | 01h |
| Parameter Table Length (in double word) | How many DWORDs in the Parameter table | 13h | 31:24 | 04h | 04h |
| Parameter Table Pointer (PTP) | First address of Macronix Flash Parameter table | 14h | 07:00 | 60h | 60h |
|  |  | 15h | 15:08 | 00h | 00h |
|  |  | 16h | 23:16 | 00h | 00h |
| Unused |  | 17h | 31:24 | FFh | FFh |

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Table 11. Parameter Table (0): JEDEC Flash Parameter Tables
SFDP Table below is for MX25U4033EBAI-12G, MX25U4033EM1I-12G, MX25U4033EZNI-12G, MX25U4033EZUI-12G and MX25U4033EZBI-12G

| Description | Comment | Add (h) <br> (Byte) | $\begin{array}{\|c\|} \hline \text { DW Add } \\ \text { (Bit) } \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \text { Data (h/b) } \\ \text { (Note1) } \\ \hline \end{array}$ | Data <br> (h) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Block/Sector Erase sizes | 00: Reserved, 01: 4KB erase, 10: Reserved, <br> 11: not support 4KB erase | 30h | 01:00 | 01b | E5h |
| Write Granularity | 0: 1Byte, 1: 64Byte or larger |  | 02 | 1b |  |
| Write Enable Instruction Required for Writing to Volatile Status Registers | 0 : not required <br> 1: required 00 h to be written to the status register |  | 03 | Ob |  |
| Write Enable Opcode Select for Writing to Volatile Status Registers | 0: use 50h opcode, <br> 1: use 06h opcode <br> Note: If target flash status register is nonvolatile, then bits 3 and 4 must be set to 00b. |  | 04 | Ob |  |
| Unused | Contains 111b and can never be changed |  | 07:05 | 111b |  |
| 4KB Erase Opcode |  | 31h | 15:08 | 20h | 20h |
| (1-1-2) Fast Read (Note2) | 0=not support 1=support | 32h | 16 | Ob | B0h |
| Address Bytes Number used in addressing flash array | 00: 3Byte only, 01: 3 or 4Byte, 10: 4Byte only, 11: Reserved |  | 18:17 | 00b |  |
| Double Transfer Rate (DTR) Clocking | 0=not support 1=support |  | 19 | Ob |  |
| (1-2-2) Fast Read | 0=not support 1=support |  | 20 | 1b |  |
| (1-4-4) Fast Read | $0=$ not support 1=support |  | 21 | 1b |  |
| (1-1-4) Fast Read | 0=not support 1=support |  | 22 | Ob |  |
| Unused |  |  | 23 | 1b |  |
| Unused |  | 33h | 31:24 | FFh | FFh |
| Flash Memory Density |  | 37h:34h | 31:00 | 003F FF | FFh |
| (1-4-4) Fast Read Number of Wait states (Note3) | $\begin{aligned} & 0 \text { 0000b: Not supported; } 0 \text { 0100b: } 4 \\ & 0 \\ & 0 \end{aligned}$ | 38h | 04:00 | 0 0100b | 44h |
| (1-4-4) Fast Read Number of Mode Bits (Note4) | Mode Bits: 000b: Not supported; 010b: 2 bits |  | 07:05 | 010b |  |
| (1-4-4) Fast Read Opcode |  | 39h | 15:08 | EBh | EBh |
| (1-1-4) Fast Read Number of Wait states | 0 0000b: Not supported; 0 0100b: 4 0 0110b: 6; 0 1000b: 8 | 3Ah | 20:16 | 0 0000b | 00h |
| (1-1-4) Fast Read Number of Mode Bits | Mode Bits: 000b: Not supported; 010b: 2 bits |  | 23:21 | 000b |  |
| (1-1-4) Fast Read Opcode |  | 3Bh | 31:24 | FFh | FFh |

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SFDP Table below is for MX25U4033EBAI-12G, MX25U4033EM1I-12G, MX25U4033EZNI-12G, MX25U4033EZUI-12G and MX25U4033EZBI-12G

| Description | Comment | Add (h) (Byte) | $\begin{gathered} \hline \text { DW Add } \\ \text { (Bit) } \end{gathered}$ | $\begin{gathered} \hline \text { Data (h/b) } \\ \text { (Note1) } \\ \hline \end{gathered}$ | Data <br> (h) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| (1-1-2) Fast Read Number of Wait states | 0 0000b: Not supported; 0 0100b: 4 0 0110b: 6; 0 1000b: 8 | 3Ch | 04:00 | 0 0000b | 00h |
| (1-1-2) Fast Read Number of Mode Bits | Mode Bits: <br> 000b: Not supported; 010b: 2 bits |  | 07:05 | 000b |  |
| (1-1-2) Fast Read Opcode |  | 3Dh | 15:08 | FFh | FFh |
| (1-2-2) Fast Read Number of Wait states | 0 0000b: Not supported; 0 0100b: 4 0 0110b: 6; 0 1000b: 8 | 3Eh | 20:16 | 0 0100b | 04h |
| (1-2-2) Fast Read Number of Mode Bits | Mode Bits: 000b: Not supported; 010b: 2 bits |  | 23:21 | 000b |  |
| (1-2-2) Fast Read Opcode |  | 3Fh | 31:24 | BBh | BBh |
| (2-2-2) Fast Read | 0=not support 1=support | 40h | 00 | Ob | EEh |
| Unused |  |  | 03:01 | 111b |  |
| (4-4-4) Fast Read | 0=not support 1=support |  | 04 | Ob |  |
| Unused |  |  | 07:05 | 111b |  |
| Unused |  | 43h:41h | 31:08 | FFh | FFh |
| Unused |  | 45h:44h | 15:00 | FFh | FFh |
| (2-2-2) Fast Read Number of Wait states | 0 0000b: Not supported; 0 0100b: 4 0 0110b: 6; 0 1000b: 8 | 46h | 20:16 | 0 0000b | 00h |
| (2-2-2) Fast Read Number of Mode Bits | Mode Bits: <br> 000b: Not supported; 010b: 2 bits |  | 23:21 | 000b |  |
| (2-2-2) Fast Read Opcode |  | 47h | 31:24 | FFh | FFh |
| Unused |  | 49h:48h | 15:00 | FFh | FFh |
| (4-4-4) Fast Read Number of Wait states | 0 0000b: Not supported; 0 0100b: 4 0 0110b: 6; 0 1000b: 8 | 4Ah | 20:16 | 0 0000b | 00h |
| (4-4-4) Fast Read Number of Mode Bits | Mode Bits: <br> 000b: Not supported; 010b: 2 bits |  | 23:21 | 000b |  |
| (4-4-4) Fast Read Opcode |  | 4Bh | 31:24 | FFh | FFh |
| Sector Type 1 Size | Sector/block size $=2^{\wedge} \mathrm{N}$ bytes (Note5) 0Ch: 4KB; 0Fh: 32KB; 10h: 64KB | 4Ch | 07:00 | 0Ch | OCh |
| Sector Type 1 erase Opcode |  | 4Dh | 15:08 | 20h | 20h |
| Sector Type 2 Size | Sector/block size $=2^{\wedge} N$ bytes 00h: N/A; 0Fh: 32KB; 10h: 64KB | 4Eh | 23:16 | 0Fh | OFh |
| Sector Type 2 erase Opcode |  | 4Fh | 31:24 | 52h | 52h |
| Sector Type 3 Size | Sector/block size $=2^{\wedge} \mathrm{N}$ bytes 00h: N/A; 0Fh: 32KB; 10h: 64KB | 50h | 07:00 | 10h | 10h |
| Sector Type 3 erase Opcode |  | 51h | 15:08 | D8h | D8h |
| Sector Type 4 Size | 00h: N/A, This sector type doesn't exist | 52h | 23:16 | 00h | 00h |
| Sector Type 4 erase Opcode |  | 53h | 31:24 | FFh | FFh |

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Table 12. Parameter Table (1): Macronix Flash Parameter Tables
SFDP Table below is for MX25U4033EBAI-12G, MX25U4033EM1I-12G, MX25U4033EZNI-12G, MX25U4033EZUI-12G and MX25U4033EZBI-12G

| Description | Comment | Add (h) (Byte) | DW Add (Bit) | $\begin{array}{\|c\|} \hline \text { Data (h/b) } \\ \text { (Note1) } \end{array}$ | Data <br> (h) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Vcc Supply Maximum Voltage | $\begin{aligned} & 2000 \mathrm{~h}=2.000 \mathrm{~V} \\ & 2700 \mathrm{~h}=2.700 \mathrm{~V} \\ & 3600 \mathrm{~h}=3.600 \mathrm{~V} \end{aligned}$ | 61h:60h | $\begin{aligned} & \text { 07:00 } \\ & \text { 15:08 } \end{aligned}$ | $\begin{aligned} & 00 \mathrm{~h} \\ & 20 \mathrm{~h} \end{aligned}$ | $\begin{aligned} & \text { 00h } \\ & 20 \mathrm{~h} \end{aligned}$ |
| Vcc Supply Minimum Voltage | $\begin{aligned} & 1650 \mathrm{~h}=1.650 \mathrm{~V}, 1750 \mathrm{~h}=1.750 \mathrm{~V} \\ & 2250 \mathrm{~h}=2.250 \mathrm{~V}, 230 \mathrm{~h}=2.300 \mathrm{~V} \\ & 2350 \mathrm{~h}=2.350 \mathrm{~V}, 2650 \mathrm{~h}=2.650 \mathrm{~V} \\ & 2700 \mathrm{~h}=2.700 \mathrm{~V} \end{aligned}$ | 63h:62h | $\begin{aligned} & 23: 16 \\ & 31: 24 \end{aligned}$ | $\begin{aligned} & \text { 50h } \\ & \text { 16h } \end{aligned}$ | $\begin{aligned} & 50 \mathrm{~h} \\ & 16 \mathrm{~h} \end{aligned}$ |
| H/W Reset\# pin | 0=not support 1=support | 65h:64h | 00 | 0b | 4FF6h |
| H/W Hold\# pin | 0=not support 1=support |  | 01 | 1b |  |
| Deep Power Down Mode | 0=not support 1=support |  | 02 | 1b |  |
| S/W Reset | 0=not support 1=support |  | 03 | 0b |  |
| S/W Reset Opcode | Reset Enable (66h) should be issued before Reset Opcode |  | 11:04 | $\begin{gathered} \hline 1111 \text { 1111b } \\ \text { (FFh) } \end{gathered}$ |  |
| Program Suspend/Resume | 0=not support 1=support |  | 12 | Ob |  |
| Erase Suspend/Resume | 0=not support 1=support |  | 13 | 0b |  |
| Unused |  |  | 14 | 1b |  |
| Wrap-Around Read mode | 0=not support 1=support |  | 15 | Ob |  |
| Wrap-Around Read mode Opcode |  | 66h | 23:16 | FFh | FFh |
| Wrap-Around Read data length | 08h:support 8B wrap-around read 16h:8B\&16B 32h:8B\&16B\&32B 64h:8B\&16B\&32B\&64B | 67h | 31:24 | FFh | FFh |
| Individual block lock | 0=not support 1=support | 6Bh:68h | 00 | 1b | C8D9h |
| Individual block lock bit (Volatile/Nonvolatile) | $0=$ Volatile 1=Nonvolatile |  | 01 | 0b |  |
| Individual block lock Opcode |  |  | 09:02 | $\begin{gathered} \hline 00110110 \mathrm{~b} \\ (36 \mathrm{~h}) \end{gathered}$ |  |
| Individual block lock Volatile protect bit default protect status | $0=$ protect $1=$ unprotect |  | 10 | 0b |  |
| Secured OTP | 0=not support 1=support |  | 11 | 1b |  |
| Read Lock | 0=not support 1=support |  | 12 | 0b |  |
| Permanent Lock | 0=not support 1=support |  | 13 | 0b |  |
| Unused |  |  | 15:14 | 11b |  |
| Unused |  |  | 31:16 | FFh | FFh |
| Unused |  | 6Fh:6Ch | 31:00 | FFh | FFh |

Note 1: $h / b$ is hexadecimal or binary.
Note 2: ( $\mathbf{x}-\mathbf{y}-\mathrm{z}$ ) means I/O mode nomenclature used to indicate the number of active pins used for the opcode (x), address $(y)$, and data $(z)$. At the present time, the only valid Read SFDP instruction modes are: (1-1-1), (2-2-2), and (4-4-4)
Note 3: Wait States is required dummy clock cycles after the address bits or optional mode bits.
Note 4: Mode Bits is optional control bits that follow the address bits. These bits are driven by the system controller if they are specified. (eg,read performance enhance toggling bits)
Note 5: $4 \mathrm{~KB}=2^{\wedge} 0 \mathrm{Ch}, 32 \mathrm{~KB}=2^{\wedge} 0 \mathrm{Fh}, 64 \mathrm{~KB}=2^{\wedge} 10 \mathrm{~h}$
Note 6: All unused and undefined area data is blank FFh for SFDP Tables that are defined in Parameter Identification Header. All other areas beyond defined SFDP Table are reserved by Macronix.

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## 11. POWER-ON STATE

The device is at below states when power-up:

- Standby Mode ( please note it is not Deep Power Down Mode)
- Write Enable Latch (WEL) bit is reset

The device must not be selected during power-up and power-down stage unless the VCC achieves below correct level:

- VCC minimum at power-up stage and then after a delay of tVSL
- GND at power-down

Please note that a pull-up resistor on CS\# may ensure a safe and proper power-up/down level.
An internal power-on reset (POR) circuit may protect the device from data corruption and inadvertent data change during power up state.

For further protection on the device, if the VCC does not reach the VCC minimum level, the correct operation is not guaranteed. The read, write, erase, and program command should be sent after the below time delay:

- tVSL after VCC reached VCC minimum level

Please refer to "Figure 36. Power-up Timing" .
Note:

- To stabilize the VCC level, the VCC rail decoupled by a suitable capacitor close to package pins is recommended. (generally around 0.1 uF )

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## 12. ELECTRICAL SPECIFICATIONS

## 12-1. Absolute Maximum Ratings

| RATING | VALUE |  |
| :--- | :---: | :---: |
| Ambient Operating Temperature | Industrial grade | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ |
| Storage Temperature | $-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ |  |
| Applied Input Voltage | -0.5 V to $\mathrm{VCC}+0.5 \mathrm{~V}$ |  |
| Applied Output Voltage | -0.5 V to $\mathrm{VCC}+0.5 \mathrm{~V}$ |  |
| VCC to Ground Potential | -0.5 V to 2.5 V |  |

## NOTICE:

1. Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is stress rating only and functional operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended period may affect reliability.
2. Specifications contained within the following tables are subject to change.
3. During voltage transitions, all pins may overshoot to VCC +1.0 V or -1.0 V for period up to 20 ns .

Figure 7. Maximum Negative Overshoot Waveform


Figure 8. Maximum Positive Overshoot Waveform


## 12-2. Capacitance

$\mathrm{TA}=25^{\circ} \mathrm{C}, \mathrm{f}=1.0 \mathrm{MHz}$

| SYMBOL | PARAMETER | MIN. | TYP | MAX. | UNIT | CONDITIONS |
| :---: | :--- | :---: | :---: | :---: | :---: | :--- |
| CIN | Input Capacitance |  |  | 6 | pF | VIN $=0 \mathrm{~V}$ |
| COUT | Output Capacitance |  |  | 8 | pF | VOUT $=0 \mathrm{~V}$ |

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Figure 9. Input Test Waveforms and Measurement Level


Figure 10. Output Loading


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Table 13. DC Characteristics
Temperature $=-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}, \mathrm{VCC}=1.65 \mathrm{~V} \sim 2.0 \mathrm{~V}$ )

| SYMBOL | PARAMETER | NOTES | MIN. | TYP. | MAX. | UNITS | TEST CONDITIONS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ILI | Input Load Current | 1 |  |  | $\pm 2$ | uA | $\begin{aligned} & \text { VCC = VCC Max, } \\ & \text { VIN = VCC or GND } \end{aligned}$ |
| ILO | Output Leakage Current | 1 |  |  | $\pm 2$ | uA | $\begin{aligned} & \text { VCC = VCC Max, } \\ & \text { VOUT = VCC or GND } \end{aligned}$ |
| ISB1 | VCC Standby Current | 1 |  | 8 | 30 | uA | $\begin{aligned} & \text { VIN = VCC or GND, } \\ & \text { CS\# = VCC } \end{aligned}$ |
| ISB2 | Deep Power-down Current |  |  | 2 | 8 | uA | $\begin{aligned} & \text { VIN = VCC or GND, } \\ & \text { CS\# = VCC } \end{aligned}$ |
| ICC1 | VCC Read | 1 |  |  | 12 | mA | $\mathrm{f}=80 \mathrm{MHz}$, <br> SCLK=0.1VCC/0.9VCC, <br> SO=Open |
|  |  |  |  |  | 7 | mA | $\begin{aligned} & \mathrm{f}=33 \mathrm{MHz}, \\ & \mathrm{SCLK}=0.1 \mathrm{VCC} / 0.9 \mathrm{VCC}, \\ & \mathrm{SO}=\text { Open } \end{aligned}$ |
| ICC2 | VCC Program Current (PP) | 1 |  | 20 | 25 | mA | Program in Progress, $\operatorname{cs\# }=\mathrm{VCc}$ |
| ICC3 | VCC Write Status <br> Register (WRSR) Current |  |  | 8 | 20 | mA | Program status register in progress, CS\#=VCC |
| ICC4 | VCC Sector/Block (32K, 64K) Erase Current (SE/BE/BE32K) | 1 |  | 20 | 25 | mA | Erase in Progress, CS\#=VCC |
| ICC5 | VCC Chip Erase Current (CE) | 1 |  | 20 | 25 | mA | Erase in Progress, CS\#=VCC |
| VIL | Input Low Voltage |  | -0.5 |  | 0.3VCC | V |  |
| VIH | Input High Voltage |  | 0.7VCC |  | VCC+0.4 | V |  |
| VOL | Output Low Voltage |  |  |  | 0.2 | V | $\mathrm{IOL}=100 \mathrm{uA}$ |
| VOH | Output High Voltage |  | VCC-0.2 |  |  | V | $\mathrm{IOH}=-100 \mathrm{uA}$ |

Note 1. Typical values at $\mathrm{VCC}=1.8 \mathrm{~V}, \mathrm{~T}=25^{\circ} \mathrm{C}$. These currents are valid for all product versions (package and speeds).

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## Table 14. AC Characteristics

Temperature $=-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}, \mathrm{VCC}=1.65 \mathrm{~V} \sim 2.0 \mathrm{~V}$

| Symbol | Alt. | Parameter |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| fSCLK | fC | Clock Frequency for the following instructions: FAST_READ, RDSFDP, PP, SE, BE, CE, DP, RES, RDP WREN, WRDI, RDID, RDSR, WRSR |  | D.C. |  | 80 | MHz |
| fRSCLK | fR | Clock Frequency for READ instructions |  |  |  | 50 | MHz |
| fTSCLK | fT | Clock Frequency for 2READ instructions |  |  |  | 80 | MHz |
|  | fQ | Clock Frequency for 4READ instructions |  |  |  | 70 | MHz |
| f4PP |  | Clock Frequency for 4PP (Quad page program) |  |  |  | 70 | MHz |
| $\mathrm{tCH}^{(1)}$ | tCLH | Clock High Time | Serial (fSCLK) | 6 |  |  | ns |
|  |  |  | Normal Read (fRSCLK) | 9 |  |  | ns |
|  |  |  | 4PP (70MHz) | 7 |  |  |  |
| $\mathrm{tCL}^{(1)}$ | tCLL | Clock Low Time | Serial (fSCLK) | 6 |  |  | ns |
|  |  |  | Normal Read (fRSCLK) | 9 |  |  |  |
|  |  |  | 4PP (70MHz) | 7 |  |  | ns |
| $\mathrm{tCLCH}^{(2)}$ |  | Clock Rise Time (peak to peak) |  | 0.1 |  |  | V/ns |
| $\mathrm{tCHCL}^{(2)}$ |  | Clock Fall Time (peak to peak) |  | 0.1 |  |  | V/ns |
| tSLCH | tCSS | CS\# Active Setup Time (relative to SCLK) |  | 7 |  |  | ns |
| tCHSL |  | CS\# Not Active Hold Time (relative to SCLK) |  | 5 |  |  | ns |
| tDVCH | tDSU | Data In Setup Time |  | 2 |  |  | ns |
| tCHDX | tDH | Data In Hold Time |  | 5 |  |  | ns |
| tCHSH |  | CS\# Active Hold Time (relative to SCLK) |  | 5 |  |  | ns |
| tSHCH |  | CS\# Not Active Setup Time (relative to SCLK) |  | 7 |  |  | ns |
| tSHSL | tCSH | CS\# Deselect Time | Read | 12 |  |  | ns |
|  |  |  | Write/Erase/Program | 30 |  |  | ns |
| tSHQZ ${ }^{(2)}$ | tDIS | Output Disable Time |  |  |  | 8 | ns |
| tHLCH |  | HOLD\# Active Setup Time (relative to SCLK) |  | 4 |  |  | ns |
| tCHHH |  | HOLD\# Active Hold Time (relative to SCLK) |  | 4 |  |  | ns |
| tHHCH |  | HOLD\# Not Active Setup Time (relative to SCLK) |  | 4 |  |  | ns |
| tCHHL |  | HOLD\# Not Active Hold Time (relative to SCLK) |  | 4 |  |  | ns |
| tHHQX | tLZ | HOLD\# to Output Low-Z |  |  |  | 8 | ns |
| tHLQZ | tHZ | HOLD\# to Output High-Z |  |  |  | 8 | ns |
| tCLQV | tV | Clock Low to Output Valid Loading: 30pF/15pF | Loading: 30pF |  |  | 8 | ns |
|  |  |  | Loading: 15pF |  |  | 6 | ns |
| tCLQX | tHO | Output Hold Time |  | 0 |  |  | ns |
| tWHSL ${ }^{(3)}$ |  | Write Protect Setup Time |  | 20 |  |  | ns |
| $\mathrm{tSHWL}^{(3)}$ |  | Write Protect Hold Time |  | 100 |  |  | ns |
| tDP ${ }^{(2)}$ |  | CS\# High to Deep Power-down Mode |  |  |  | 10 | us |
| tRES1 ${ }^{(2)}$ |  | CS\# High to Standby Mode without Electronic Signature Read |  |  |  | 10 | us |
| tRES2 ${ }^{(2)}$ |  | CS\# High to Standby Mode with Electronic Signature Read |  |  |  | 10 | us |
| tW |  | Write Status Register Cycle Time |  |  |  | 40 | ms |
| tBP |  | Byte-Program |  |  | 10 | 30 | us |
| tPP |  | Page Program Cycle Time |  |  | 1.2 | 3 | ms |
| tSE |  | Sector Erase Cycle Time |  |  | 30 | 200 | ms |
| tBE32 |  | Block Erase (32KB) Cycle Time |  |  | 200 | 1000 | ms |
| tBE |  | Block Erase (64KB) Cycle Time |  |  | 500 | 2000 | ms |
| tCE |  | Chip Erase Cycle Time |  |  | 2.5 | 5 | S |

## Notes:

1. $\mathrm{tCH}+\mathrm{tCL}$ must be greater than or equal to 1 / Frequency.
2. Value guaranteed by characterization, not $100 \%$ tested in production.
3. Only applicable as a constraint for a WRSR instruction when SRWD is set at 1.
4. Test condition is shown as "Figure 9. Input Test Waveforms and Measurement Level" and "Figure 10. Output Loading".

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## 13. TIMING ANALYSIS

Figure 11. Serial Input Timing


Figure 12. Output Timing


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Figure 13. WP\# Setup Timing and Hold Timing during WRSR when SRWD=1


Figure 14. Write Enable (WREN) Sequence (Command 06)


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Figure 15. Write Disable (WRDI) Sequence (Command 04)


Figure 16. Read Identification (RDID) Sequence (Command 9F)


Figure 17. Read Status Register (RDSR) Sequence (Command 05)


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Figure 18. Write Status Register (WRSR) Sequence (Command 01)


Figure 19. Read Data Bytes (READ) Sequence (Command 03) (50MHz)


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Figure 20. Read at Higher Speed (FAST_READ) Sequence (Command 0B)


Figure 21. $2 \times \mathrm{I} / \mathrm{O}$ Read Mode Sequence (Command BB)


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Figure 22. 4 x l/O Read Mode Sequence (Command EB)


Note:

1. Hi-impedance is inhibited for the two clock cycles.
2. $P 7 \neq P 3, P 6 \neq P 2, P 5 \neq P 1 \& P 4 \neq P 0$ (Toggling) is inhibited.

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Figure 23.4 x I/O Read Enhance Performance Mode Sequence (Command EB)


Note: 1. Performance enhance mode, if P7\#P3 \& P6\#P2 \& P5\#P1 \& P4\#P0 (Toggling), ex: A5, 5A, 0F, performance enhance recommend to keep 1 or 0 in performance enhance indicator.
2. Reset the performance enhance mode, if $\mathrm{P} 7=\mathrm{P} 3$ or $\mathrm{P} 6=\mathrm{P} 2$ or $\mathrm{P} 5=\mathrm{P} 1$ or $\mathrm{P} 4=\mathrm{P} 0$ (Not Toggling), ex: AA , 00, FF

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Figure 24. Page Program (PP) Sequence (Command 02)


Figure $25.4 \times \mathrm{I} / \mathrm{O}$ Page Program (4PP) Sequence (Command 38)
SS\#

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Figure 26. Sector Erase (SE) Sequence (Command 20)


Figure 27. Block Erase 32KB (BE32K) Sequence (Command 52)


Figure 28. Block Erase (BE) Sequence (Command D8)


Figure 29. Chip Erase (CE) Sequence (Command 60 or C7)

CS\#

sı


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Figure 30. Deep Power-down (DP) Sequence (Command B9)


Figure 31. RDP and Read Electronic Signature (RES) Sequence (Command AB)


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Figure 32. Release from Deep Power-down (RDP) Sequence (Command AB)


Figure 33. Read Electronic Manufacturer \& Device ID (REMS) Sequence (Command 90/EF/DF)


Notes:
(1) $\mathrm{ADD}=00 \mathrm{H}$ will output the manufacturer's ID first and $\mathrm{ADD}=01 \mathrm{H}$ will output device ID first.

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Figure 34. Read Security Register (RDSCUR) Sequence (Command 2B)


Figure 35. Write Security Register (WRSCUR) Sequence (Command 2F)


Figure 36. Power-up Timing


Note: VCC (max.) is 2.0 V and VCC (min.) is 1.65 V .

Table 15. Power-Up Timing

| Symbol | Parameter | Min. | Max. | Unit |
| :--- | :--- | :---: | :---: | :---: |
| tVSL $^{(1)}$ | VCC(min) to CS\# low (VCC Rise Time) | 300 |  | us |

Note: 1. The parameters is characterized only.

## INITIAL DELIVERY STATE

The device is delivered with the memory array erased: all bits are set to 1 (each byte contains FFh). The Status Register contains 00h (all Status Register bits are 0).

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## 14. OPERATING CONDITIONS

## At Device Power-Up and Power-Down

AC timing illustrated in "Figure 37. AC Timing at Device Power-Up" and "Figure 38. Power-Down Sequence" are for the supply voltages and the control signals at device power-up and power-down. If the timing in the figures is ignored, the device will not operate correctly.

During power-up and power-down, CS\# needs to follow the voltage applied on VCC to keep the device not to be selected. The CS\# can be driven low when VCC reach Vcc(min.) and wait a period of tVSL.

Figure 37. AC Timing at Device Power-Up


| Symbol | Parameter | Notes | Min. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| tVR | VCC Rise Time | 1 | 20 | 500000 | us $/ \mathrm{V}$ |

## Notes:

1. Sampled, not 100\% tested.
2. For AC spec tCHSL, tSLCH, tDVCH, tCHDX, tSHSL, tCHSH, tSHCH, tCHCL, tCLCH in the figure, please refer to "Table 14. AC Characteristics".

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Figure 38. Power-Down Sequence
During power-down, CS\# needs to follow the voltage drop on VCC to avoid mis-operation.


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## 15. ERASE AND PROGRAMMING PERFORMANCE

| PARAMETER | Min. | TYP. ${ }^{(1)}$ | Max. ${ }^{(2)}$ | UNIT |
| :--- | :---: | :---: | :---: | :---: |
| Write Status Register Cycle Time |  |  | 40 | ms |
| Sector Erase Cycle Time (4KB) |  | 30 | 200 | ms |
| Block Erase Cycle Time (32KB) |  | 200 | 1000 | ms |
| Block Erase Cycle Time (64KB) |  | 500 | 2000 | ms |
| Chip Erase Cycle Time |  | 2.5 | 5 | s |
| Byte Program Time (via page program command) |  | 10 | 30 | us |
| Page Program Time |  | 1.2 | 3 | ms |
| Erase/Program Cycle |  | 100,000 |  | cycles |

Note:

1. Typical program and erase time assumes the following conditions: $25^{\circ} \mathrm{C}, 1.8 \mathrm{~V}$, and checkerboard pattern.
2. Under worst conditions of $85^{\circ} \mathrm{C}$ and 1.65 V .
3. System-level overhead is the time required to execute the first-bus-cycle sequence for the programming command.

## 16. DATA RETENTION

| PARAMETER | Condition | Min. | Max. | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| Data retention | $55^{\circ} \mathrm{C}$ | 20 |  | years |

## 17. LATCH-UP CHARACTERISTICS

|  | MIN. | MAX. |
| :--- | :---: | :---: |
| Input Voltage with respect to GND on all power pins, SI, CS\# | -1.0 V | 2 VCCmax |
| Input Voltage with respect to GND on SO | -1.0 V | VCC +1.0 V |
| Current | -100 mA | +100 mA |

Includes all pins except VCC. Test conditions: $\mathrm{VCC}=1.8 \mathrm{~V}$, one pin at a time.

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18. ORDERING INFORMATION

| PART NO. | CLOCK (MHz) | TEMPERATURE | PACKAGE | Remark |
| :---: | :---: | :---: | :---: | :---: |
| MX25U4033EM1I-12G | 80 | $-40^{\circ} \mathrm{C} \sim 85^{\circ} \mathrm{C}$ | $8-S O P$ <br> $(150 \mathrm{mil})$ |  |
| MX25U4033EZUI-12G | 80 | $-40^{\circ} \mathrm{C} \sim 85^{\circ} \mathrm{C}$ | $8-\mathrm{USON}$ <br> $(4 \times 4 \mathrm{~mm})$ |  |
| MX25U4033EZBI-12G | 80 | $-40^{\circ} \mathrm{C} \sim 85^{\circ} \mathrm{C}$ | $8-\mathrm{USON}$ <br> $(4 \times 3 \mathrm{~mm})$ |  |
| MX25U4033EZNI-12G | 80 | $-40^{\circ} \mathrm{C} \sim 85^{\circ} \mathrm{C}$ | $8-W S O N$ <br> $(6 \times 5 \mathrm{~mm})$ |  |
| MX25U4033EBAI-12G | 80 | $-40^{\circ} \mathrm{C} \sim 85^{\circ} \mathrm{C}$ | $8-\mathrm{WLCSP}$ |  |

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## 19. PART NAME DESCRIPTION



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## 20. PACKAGE INFORMATION

## 20-1. 8-pin SOP ( 150 mil )

Title: Package Outline for SOP 8L (150MIL)


Dimensions (inch dimensions are derived from the original mm dimensions)

| SYMBOL |  | A | A1 | A2 | b | C | D | E | E1 | e | L | L1 | S | $\theta$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm | Min. | --- | 0.10 | 1.35 | 0.36 | 0.15 | 4.77 | 5.80 | 3.80 |  | 0.46 | 0.85 | 0.41 | 0 |
|  | Nom. | --- | 0.15 | 1.45 | 0.41 | 0.20 | 4.90 | 5.99 | 3.90 | 1.27 | 0.66 | 1.05 | 0.54 | 5 |
|  | Max. | 1.75 | 0.20 | 1.55 | 0.51 | 0.25 | 5.03 | 6.20 | 4.00 |  | 0.86 | 1.25 | 0.67 | 8 |
| Inch | Min. | --- | 0.004 | 0.053 | 0.014 | 0.006 | 0.188 | 0.228 | 0.150 |  | 0.018 | 0.033 | 0.016 | 0 |
|  | Nom. | --- | 0.006 | 0.057 | 0.016 | 0.008 | 0.193 | 0.236 | 0.154 | 0.050 | 0.026 | 0.041 | 0.021 | 5 |
|  | Max. | 0.069 | 0.008 | 0.061 | 0.020 | 0.010 | 0.198 | 0.244 | 0.158 |  | 0.034 | 0.049 | 0.026 | 8 |


| DWG.NO. | REVISION | REFERENCE |  |  | ISSUE DATE |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | JEDEC | EIAJ |  |  |
| 6 | 6 | MS-012 |  |  |  |

## 20-2. 8-land USON ( $4 \times 4 \mathrm{~mm}$ )

Title: Package Outline for USON 8L ( $4 \times 4 \times 0.6 \mathrm{MM}$, LEAD PITCH 0.8MM)



## SIDE VIEW

Dimensions (inch dimensions are derived from the original mm dimensions)
*1 : This package has exposed metal pad underneath the package, it can't contact to metal trace or pad on board.
*2 : The exposed pad size must not violate the min. metal separtion requirement, 0.2 mm with terminals.

| SYMBOL <br> UNIT |  | A | A1 | A2 | b | D | D1 | E | E1 | L | e | y |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm | Min. | 0.50 | --- | --- | 0.25 | 3.90 | 2.90 | 3.90 | 2.20 | 0.35 | --- | 0.00 |
|  | Nom. | 0.55 | 0.04 | 0.40 | 0.30 | 4.00 | 3.00 | 4.00 | 2.30 | 0.40 | 0.80 | --- |
|  | Max. | 0.60 | 0.05 | 0.43 | 0.35 | 4.10 | 3.10 | 4.10 | 2.40 | 0.45 | --- | 0.08 |
| Inch | Min. | 0.020 | --- | --- | 0.010 | 0.154 | 0.114 | 0.154 | 0.087 | 0.014 | --- | 0.00 |
|  | Nom. | 0.022 | 0.002 | 0.016 | 0.011 | 0.157 | 0.118 | 0.157 | 0.091 | 0.016 | 0.031 | --- |
|  | Max. | 0.024 | 0.002 | 0.017 | 0.014 | 0.161 | 0.122 | 0.161 | 0.094 | 0.018 | --- | 0.003 |


| DWG.NO. | REVISION | REFERENCE |  |  | ISSUE DATE |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | JEDEC | EIAJ |  |  |
| $6110-3601$ | 3 | MO-252 |  |  | $2008 / 03 / 12$ |

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## 20-3. 8-land USON (4x3mm)

Package Outline for USON 8L (4×3x0.60MM, LEAD PITCH 0.8MM)


SIDE VIEW

## TOP VIEW



BOTTOM VIEW


## DETAIL A

## Note:

This package has an exposed metal pad underneath the package. It is recommended to leave the metal pad floating or to connect it to the same ground as the GND pin of the package. Do not connect the metal pad to any other voltage or signal line on the PCB. Avoid placing vias or traces underneath the metal pad. Connection of this metal pad to any other voltage or signal line can result in shorts and/or electrical malfunction of the device.

Dimensions (inch dimensions are derived from the original mm dimensions)

| $\qquad$ |  | A | A1 | A2 | b | D | D1 | E | E1 | L | e | y |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm | Min. | 0.50 | --- | --- | 0.25 | 3.90 | 0.70 | 2.90 | 0.10 | 0.55 | --- | 0.00 |
|  | Nom. | 0.55 | 0.02 | 0.15 | 0.30 | 4.00 | 0.80 | 3.00 | 0.20 | 0.60 | 0.80 | --- |
|  | Max. | 0.60 | 0.05 | --- | 0.35 | 4.10 | 0.90 | 3.10 | 0.30 | 0.65 | --- | 0.08 |
| Inch | Min. | 0.020 | --- | --- | 0.010 | 0.154 | 0.028 | 0.114 | 0.004 | 0.022 | --- | 0.00 |
|  | Nom. | 0.022 | 0.001 | 0.006 | 0.011 | 0.158 | 0.032 | 0.118 | 0.008 | 0.024 | 0.031 | --- |
|  | Max. | 0.024 | 0.002 | --- | 0.014 | 0.161 | 0.035 | 0.122 | 0.012 | 0.026 | --- | 0.003 |


| Dwg. No. | Revision | Reference |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | JEDEC | EIAJ |  |  |
| $6110-3603$ | 1 | MO-220 |  |  |  |

## 20-4. 8-land WSON ( $6 \times 5 \mathrm{~mm}$ )

Doc. Title: Package Outline for WSON 8L (6x5x0.8MM, LEAD PITCH 1.27MM)


Note:
This package has an exposed metal pad underneath the package. It is recommended to leave the metal pad floating or to connect it to the same ground as the GND pin of the package. Do not connect the metal pad to any other voltage or signal line on the PCB. Avoid placing vias or traces underneath the metal pad. Connection of this metal pad to any other voltage or signal line can result in shorts and/or electrical malfunction of the device.

Dimensions (inch dimensions are derived from the original mm dimensions)

| UNIT |  | A | A1 | A2 | b | D | D1 | E | E1 | L | e | y |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mm | Min. | 0.70 | --- | --- | 0.35 | 5.90 | 3.30 | 4.90 | 3.90 | 0.50 | --- | 0.00 |
|  | Nom. | --- | --- | 0.20 | 0.40 | 6.00 | 3.40 | 5.00 | 4.00 | 0.60 | 1.27 | --- |
|  | Max. | 0.80 | 0.05 | --- | 0.48 | 6.10 | 3.50 | 5.10 | 4.10 | 0.75 | --- | 0.05 |
| Inch | Min. | 0.028 | --- | --- | 0.014 | 0.232 | 0.129 | 0.193 | 0.154 | 0.020 | --- | 0.00 |
|  | Nom. | --- | --- | 0.008 | 0.016 | 0.236 | 0.134 | 0.197 | 0.157 | 0.024 | 0.05 | --- |
|  | Max. | 0.032 | 0.002 | --- | 0.019 | 0.240 | 0.138 | 0.201 | 0.161 | 0.030 | --- | 0.002 |


| Dwg. No. | Revision | Reference |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | JEDEC | EIAJ |  |  |
| $6110-3401$ | 8 | MO-220 |  |  |  |

Macronix
International Co., Ltd.

## 20-5. 8-WLCSP

Title: Package Outline for 8BALL WLCSP (BALL PITCH 0.5mm, BALL DIAMETER 0.25MM) TOP VIEW BOTTOM VIEW


Dimensions (inch dimensions are derived from the original mm dimensions)

| SYMBOL <br> UNIT |  | A | A1 | b | e |
| :---: | :---: | :---: | :---: | :---: | :---: |
| mm | Min. | 0.35 | 0.105 | 0.22 | --- |
|  | Nom. | 0.40 | 0.135 | 0.25 | 0.50 BSC |
|  | Max. | 0.45 | 0.165 | 0.28 | --- |
| Inch | Min. | 0.014 | 0.0041 | 0.009 | --- |
|  | Nom. | 0.016 | 0.0053 | 0.010 | 0.020 BSC |
|  | Max. | 0.018 | 0.0065 | 0.011 | --- |


| Dwg. No. | Revision | Reference |  |  |  |
| :---: | :---: | :---: | :---: | :--- | :--- |
|  |  | JEDEC | EIAJ |  |  |
| $6110-4603$ | 0 |  |  |  |  |

Please contact local Macronix sales channel for complete package dimensions.

## 21. REVISION HISTORY

| Revision No. | Description | Page | Date |
| :---: | :---: | :---: | :---: |
| 0.00 | 1. Initial release | All | NOV/10/2011 |
| 1.0 | 1. Removed "Advanced Information" | P5 | DEC/27/2011 |
| 1.1 | 1. Removed "Advanced Information" for P/N: MX25U4033EZNI-12G | P56 | FEB/24/2012 |
| 1.2 | 1. Added SFDP content | P35~40, 45 | MAR/20/2012 |
| 1.3 | 1. Modified Input High and Low Voltage | P44 | OCT/31/2012 |
| 1.4 | 1. Removed "Advanced Information" for P/N: MX25U4033EZUI-12G | P62 | JAN/09/2013 |
| 1.5 | 1. Updated parameters for DC Characteristics. <br> 2. Updated Erase and Programming Performance. <br> 3. Modified Absolute Maximum Ratings table. | $\begin{aligned} & \text { P5, } 44 \\ & \text { P5, } 45,61 \\ & \text { P42 } \end{aligned}$ | NOV/14/2013 |
| 1.6 | 1. Added WLCSP package and Part No. <br> 2. Modified SFDP Table wording without values change | $\begin{aligned} & \text { P6,8,62,63,67 } \\ & \text { P36~39 } \end{aligned}$ | APR/11/2014 |
| 1.7 | 1. Modified Power-up Timing figure and parameter | P41,58 | JUL/01/2014 |
| 1.8 | 1. Updated BLOCK DIAGRAM <br> 2. Added 8 -USON ( $4 \times 3 \mathrm{~mm}$ ) package and part number <br> 3. Revised Note 6 of SFDP Tables | $\begin{aligned} & \text { P9 } \\ & \text { P6,8,62~63,66 } \\ & \text { P40 } \end{aligned}$ | AUG/26/2015 |
| 1.9 | 1. Revised Note 3 to belong to Write Protect AC parameters and removed Note 3 on tSHSL, tCLCH, and tCHCL. <br> 2. Updated "9. HOLD FEATURE". <br> 3. Added internal pull high information for WP\# and HOLD\# <br> 4. Content modification | $\begin{aligned} & \text { P45 } \\ & \text { P14 } \\ & \text { P8 } \\ & \text { P11,16,21,44 } \end{aligned}$ | JAN/12/2016 |

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